

FR-F 740 EC/E1

Technical Catalogue

The new FR-F 740 frequency inverters are available with outputs from $0.75-630 \mathrm{~kW}$ and are ideal for applications with pump and fan drives.
They use a 3-phase AC power supply and have an output frequency range of $0.5-400 \mathrm{~Hz}$.

## Further Publications within the Factory Automation Range

## Technical Catalogues Frequency Inverters

Product catalogue for frequency inverters and accessories
of the FR-S 500, FR-E 500 and FR-A 500 series

## Technical Catalogues MELSERVO and Motion Controllers

Product catalogues for MR-J2 series amplifiers, servo motors and motion controllers with SSCNET connection

## PLC Technical Catalogues

Product catalogues for programmable logic controllers and accessories for the MELSEC series

## Networks Technical Catalogue

Product catalogue for Master and Slave modules as well as accessories for the use of programmable logic controllers in open networks and MELSEC networks

## HMI Technical Catalogue

Product catalogue for operator terminals, process visualisation and programming software as well as accessories

## Additional Services

You will find current information on updates, alterations, new items and technical support on MITSUBISHI ELECTRIC's web pages (www.mitsubishi-automation.com).

The products section of the MITSUBISHI home site includes various documents for the whole product range offered by MITSUBISHI ELECTRIC as well as the current version of this catalogue. All manuals and catalogues can be downloaded for your convenience. Manuals and catalogues are available in multiple language. Please check for availability.

## About this product catalogue

Due to the constantly growing product range, technical alteration, and new or changed characteristical features, this catalogue is updated frequently.
Texts, figures and diagrams shown in this product catalogue are intended exclusively for explanation and assistance in planning and ordering the frequency inverter series FR-F 700 EC/E1 and the associated accessories. Only the manuals supplied with the units are relevant for installation, commissioning and handling of the units and accessories. The information given in these documentations must be read before installation and commissioning of the units or software.
Should questions arise with regard to the planning of modules described in this product catalogue, do not hesitate to contact your nearest office listed on the last page of this document.

## FREQUENCY INVERTER FR－F 740 EC／E1

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## The FR-F 740 Frequency Inverter

Mitsubishi Electric's FR-F 740 series is a completely new range of frequency inverters with truly exceptional power conservation capabilities. These inverters are ideal for pumps, ventilation fans and applications with reduced overload requirements such as:
Air conditioning systems, e.g. in building management

- Air extraction systems
- Fans and blowers
- Hydraulics systems
- Compressors
- Sewage and drains systems
- Ground water pumps
- Heat pumps
- Drive systems with high idling rates

These inverters are very user-friendly and they are available with output ratings matched to users' real needs.
The FR-F 740 is available in versions with outputs from $0.75-640 \mathrm{~kW}$. All the inverters in the series are designed for connection to $3 \sim 380-480 \mathrm{~V} / 500 \mathrm{~V}(50 / 60 \mathrm{~Hz})$ power supplies.
The output frequency range is $0.5-400 \mathrm{~Hz}$.


## Proven Technology with Advanced New Capabilities

## Innovative performance optimisation

The drive performance of the FR-F 740 series is optimised for the special needs of fan and pump applications. Drives in applications like these are characterised by a load torque curve that increases by the square of the motor speed (variable curve). Of course, these frequency inverters can also be used for standard applications with constant load curves and a maximum overload of $150 \%$.

The outstanding features and characteristics of the FR-F 740 series include:

- Power-saving mode with display of the energy savings
- PID control
- Extended PID control with sleep and multi-motor switching functions
- Flexible 5-point V/f curve
- Continued operation after brief power failures
- Automatic restart after instantaneous power failures
- Flying start
- PTC temperature sensor input
- Switch motor to direct mains operation
- Active current limiting
- Optimum excitation control
- Regeneration avoidance function
- Traverse function
- Disable defined frequency ranges
- Selectable 2nd parameter set for different load characteristics
- Network support


## Intelligent Technology that Cuts Power Consumption

## Saving power with Mitsubishi frequency converters

Reducing consumption and optimising the utilisation of our valuable energy resources is one of the greatest global environmental challenges of our age.
Energy conservation mode is a standard feature of the intelligent controller. It dynamically adjusts the voltage to motor requirements, eliminating unnecessary power losses, which helps to further reduce power consumption. Frequency inverters are particularly effective at conserving energy when they are used to control pumps and fans.
The amount of energy conservation (hysteresis) depends on the speed/torque fluctuations. The graph below provides an impressive example of the results of
intelligent control in a fan system.


Rotational speed (= air quantity) (\%) ${ }^{100}$

## How do frequency inverters conserve energy?

The illustration below shows a blower system in which the air flow is regulated by controlling the motor with a frequency inverter instead of with a damper on the exhaust side.
The graph below compares the motor power consumption of the frequency inverter and damper solutions. At a flow rate of $60 \%$ the curve shows that the frequency inverter system consumes a full $60 \%$ less power than the motor with the damper system.

## Potential savings

In addition to the ecological benefits frequency inverters can also save a great deal of money by radically cutting power consumption.
Example:
Based on the graph on the left and an electricity price of 14 cents per kWh, the following savings can be achieved with a system using a 75 kW motor:

- Conventional mechanical solution At an air throughput of $60 \%$ the power consumption is $90 \%$, resulting in the following annual costs:
$75 \mathrm{~kW} \times 0.9 \times € 0.14 \times 24 \mathrm{~h} \times 365$ days = € 82,782
- Frequency inverter solution At an air throughput of $60 \%$ the power consumption is $30 \%$, resulting in the following annual costs:
$75 \mathrm{~kW} \times 0.3 \times € 0.14 \times 24 \mathrm{~h} \times 365$ days = € 27,594
This means that the inverter solution saves $€ 55,188$ per year compared to the conventional mechanical system!
Clearly, a frequency inverter will pay for itself in a very short time - and one must also remember that the potential savings increase with the power ratings of the motors used.


## Energy savings control

The effect of energy savings can be confirmed using the control panel, via the output terminals (CA, AM) and via networks (network option required) with the newly developed energy saving monitor.

Application with potential for power savings


## Intelligent Motor Control Functions

## Extended PID control

The FR-F 740 series supports extended PID control. This feature makes it possible to connect the process status signal to the frequency inverter as a voltage signal ( $0-10 \mathrm{~V}$ DC) or a current signal (0/4-20 mA DC) and then use the analog input calibration function of the inverter to compensate minor controller-related fluctuations.
In addition to this the frequency inverter can also control up to four motors successively. This function is programmable; for example, you can program it so that only one motor is frequency-controlled and the others are switched on and off under direct mains power as required, or you can alternate between direct mains power and frequency control for all four motors.
The graph on the right illustrates this multimotor switching function with a typical example.
When implementing an application like this you must plan the necessary number of magnetic power contactors and the required number of output signal terminals on the inverter. Care must also be taken to ensure that the mains power is never switched to the inverter output.

## Flexible 5-point V/f curve

The integrated flexible 5-point V/f curve enables you to match the torque curve perfectly to the characteristics of your machine.
Together, the optimum excitation control feature and the 5 -point $\mathrm{V} / \mathrm{f}$ curve achieve significantly increased power savings.



After switching the magnetic contactor the motor start sequence switches from M1->M2->M3 to M2->M3->M1

## Automatic restart after instantaneous power failures

In pump and fan applications normal operation can be continued automatically after brief power failures. The system simply reactivates the coasting motor and automatically accelerates it back up to its setpoint speed.
The graphic on the right shows how the frequency inverter can respond to a brief power outage. Instead of coasting down completely and stopping, the motor is automatically "caught" by the frequency in-
 verter and re-accelerated back up to its previous speed.

## Innovative Features and Functions

## Flying start

Gentle restart of a rotating motor (e.g. fan rotated by a draft), also in the opposite direction.

## PTC temperature sensor input

The motor's internal PTC temperature sensor can be connected to the inverter directly. In combination with the electronic temperature monitoring system this provides effective protection for the motor.

## Active current limiting

Tried and tested capabilities like the active current limiting feature have been retained. The characteristics of the current limiter have now been further improved to prevent unwanted triggering in response to overcurrents. Transient overcurrents, for example those generated when a motor coasting in reverse is restarted or when an input contactor is closed, will no longer cause unwanted triggering of the current limiter.

## Magnetic flux vector control

The integrated motor flux vector control system makes it possible to achieve high torques, even at low motor speeds.

## Optimum excitation control

You can also select the optimum excitation control mode, which achieves yet more power savings compared to conventional inverters designed for pump and fan applications.
The graph below demonstrates the kind of improvements that are possible with this control mode:


Optimum excitation control mode
Standard energy saving inverter
No excitation control

## Regeneration avoidance function

This function can prevent the inverter from being shut down by regenerative overvoltages when strong regenerative loads cause power to be released into the frequency inverter (for example when braking the motor or with loads that actively drive the motor).
The inverter can automatically increase the output frequency or disable the braking ramp when a programmed threshold value is reached. The response sensitivity, dynamics and working range are all adjustable.
For example, this function can prevent a shutdown with an overvoltage error when the speed of a fan controlled by the inverter is increased by the draft from another fan operating in the same ventilation duct. The function then temporarily increases the output frequency above the setpoint value.
This function can also be used to brake loads with the DC bus voltage, without using braking modules.

## Switching to direct mains operation

You can switch the motor to direct mains operation by programming the contactor relays accordingly and applying a control signal to terminals L11 and L21 of the inverter.

## Traverse function

The traverse function of the FR-F740 is designed specifically for use in yarn-winding applications in the textile industry.
This function performs a cyclical variation of the output frequency as shown in the graph on the right. The width of the fluctuation around the frequency setpoint value and the ramp times are configurable via setup parameters.
This function prevents the formation of the unwanted "bands" in the wound yarn.


## Extensive Communications Support

## Extended I/Os for additional control functions

The following I/Os are included as standard equipment on the FR-F 740:

- 12 contact inputs
- 3 analog inputs
- 5 open collector outputs
- 2 relay outputs
- 2 analog outputs

The contact inputs, open collector outputs and relay outputs can all be used for a wide range of functions.
Two of the analog inputs can be switched from current to voltage. The switching status of the input and output terminals can be displayed on the control panel.

## Remote I/Os

Instead of using the remote I/Os of a PLC you can use a network connection to both read out the status of the frequency inverter's inputs and set its outputs.

## Expansion slot

The frequency inverter has an expansion slot that can be used to install an I/O expansion module or a network module. These modules are cards that are installed by plugging them into the slot in the inverter. See page 34 for a list of available modules.

## Extended networking capabilities

The inverter comes with two serial ports as standard equipment for integration in an automation network. You can connect a standard RJ45 network cable to the PU connector. there are also RS-485 terminals inside the inverter unit for connection to a multidrop network via a normal cable, which enables inexpensive networking of up to 32 nodes.
In addition to the Mitsubishi protocol you can also use the Modbus RTU (binary) protocol.

## Programming via USB

You can configure the setup parameters and monitor the frequency inverter via an USB port with the optional USB 1.1 module.

## Support for integration in larger networks

Open communications with standard industrial bus systems can be implemented easily with optional expansion cards.
This makes it possible to integrate the frequency inverter in large-scale automation systems.

The following networks are supported by the FR-F 740:

- CC-Link
- Profibus/DP
- DeviceNet
- LON Works
- RS485 and Modbus RTU (standard)

You can find a description of the network cards on page 34.


## Environment-Friendly and Internationally Compatible

## Electromagnetic compatibility

New technologies have been used to significantly reduce the interference levels generated by this frequency inverter.
The FR-F 740 EC conforms to the strict electromagnetic compatibility regulations of the European Union (EMC Directive, Environment 2). In order to meet these standards the FR-F700 inverters are fitted with a new, integrated interference suppression filter, which can easily be deactivated with a jumper if necessary.

You can also further limit the make current and reduce network interference by fitting the input of the inverter with an optional AC reactor and a DC reactor, which is connected to special terminals on the inverter unit.
The DC reactor is included as standard equipment with models 00180 and above and must be used with them.

## Circuit boards with two coats of protective varnish

The frequency inverters with the E1 designation (standard, type 02160 and above) have circuit boards with two coats of protective varnish.
This feature is available as an option for the models up to type 01800. The twin coating on the internal PCBs provides even better protection against environmental influences. This is particularly important in applications sewage plants where the switchgear cabinets are exposed to aggressive fermentation gases that can reduce the service life of the equipment.

## International standards

The inverters of the FR-F 740 EC series are designed so that they can be used worldwide without any additional modifications or certifications.

- The units conform to the international CE, UL, CUL, Gost and CCC standards.
- User-selectable positive or negative switching logic. Users can select positive or negative switching logic for input and output signals, enabling flexible and simple adaptation of the units for varying world market requirements.
- Extended input power voltage range: $3 \sim 380-480 \mathrm{~V}$ (up to 500 V for 01800 and above), $50 / 60 \mathrm{~Hz}$ Tolerance: $-15 \% ;+10 \%$
- Multilingual programming/control unit (optional)
- Support for a variety of international industrial bus systems
- Internationally standardised, frequency inverter configuration software package for MS Windows, with multilingual user interface

These features make the FR-F 740 EC a truly international product that meets all relevant standards and can be easily adjusted for national requirements.


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## User-friendly Operation

## Easy configuration with control panel or software

The FR-DU07 control panel is included as standard equipment with all the inverters of this series. It makes operation of the inverter simple and intuitive and displays operating parameters and alarm messages. The jog shuttle "digital dial" control provides fast and efficient access to all key drive parameters.
The optional FR-PU04 control panel features a long-life LC-display with a backlight and integrated numeric keypad for direct entry of operating parameters. The user interface can be displayed in eight different languages. This panel is designed as a remote unit that is connected to the inverter with a cable. It also supports definition of user groups with which you can implement editable parameter sets that can then be selected as required for specific applications.
 VFD setup software package. Using this software you can configure, operate and monitor multiple frequency inverters, either in a network or directly from a single PC or notebook computer. (See page 21 for more details on this software package.)

## User-friendly

In addition to allowing you to enter and display configuration and control parameters the integrated control panel can also be used to monitor and display current operating data and alarm messages. The information is output on a 4 -digit LED display.
You can monitor all the current status parameters of both the inverter itself and the connected motor. Problems and malfunctions are indicated by error codes.

## One-touch operation

Simple and intuitive configuration and operation save both time and money. The control panel's jog shuttle "digital dial" control provides much faster access to all key drive parameters than would be possible with conventional buttons and keys.
You can also use the dial to continuously adjust the speed of the connected motor.

Example: Adjusting a parameter with the jog shuttle


## Removable panel with parameter copy function

The control panel is removable and can also be connected installed remotely, for example in the door of a switchgear cabinet. It also features a useful copy function with which you can copy the parameter settings of one frequency inverter to another.

## Alarm log

The control panel stores an alarm log for up to 8 alarm messages that can be displayed and checked on the panel. The alarm details in the log include frequency, current, voltage and cumulative operating time at the time of the alarm.

## Switch between direct and external control

The frequency inverter can be controlled directly via the control panel (PU mode) or via external signals (EXT mode).


## Long Service Life and Easy Maintenance

## New components for longer service life

The components of this new generation of frequency inverters are specified for a service life of 10 years (mean annual ambient temperature $40^{\circ} \mathrm{C}, 80 \%$ load in an environment free of aggressive gases, flammable gases, oil mist, dust and dirt). Among other things, this is made possible by the newly-developed, long-life cooling fans that are monitored by the inverter. The life of the cooling fans can also be made significantly longer by using Parameter 244, which controls the selective shutdown feature.

## Modern diagnostics functions further extend service life

The ageing of the main circuit capacitors, the control circuit power capacitor, the internal cooling fans and the inrush current limiter circuit can be checked with the monitoring functions. If the inrush resistor overheats an alarm is displayed.
The alarms for the main circuit capacitors, control circuit capacitor, inrush current limiter and internal fans can all be output to a network or via the optional FR-A7AY module.
This makes it possible to prevent malfunctions by configuring diagnostics alarms to be triggered when the end of the service life is reached.

The inverter also has an internal program that can evaluate the ageing of the main circuit capacitors. This feature is only available when a motor is connected to the inverter.

## Service timer

The frequency inverters of this series all have an integrated service timer that automatically triggers an alarm after a set number of operating hours. This feature can be used for monitoring the frequency inverter itself or a peripheral component. The values of the mean output current and the service timer can also be output as analog signals.

## Improved handling

The main cooling fan is easily accessible at the top of the inverter unit, allowing quick and easy replacement without removal of the connection cables.
The cable guide comb (see illustration) is removable and makes routing the cables quick and trouble-free. After the cables have been connected the cover can then be replaced (for frequency inverters up to type 00620).

## Easy replacement

The terminal block for the control circuit connections is removable to enable easy replacement of the inverter unit for servicing, which greatly facilitates both installation and maintenance work. You can also use the removable terminal block of the FR-F500 series, which is compatible to the FR-F700 series. However, please note that some of the functions of the FR-F700 series are not available when you use a terminal block from the FR-F500 series.

Replacement of the terminal block:


## Specifications FR-F 740-00023 to -01160

| Series |  |  |  | FR-F 740 |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | 00023 | 00038 | 00052 | 00083 | 00126 | 00170 | 00250 | 00310 | 00380 | 00470 | 00620 | 00770 | 00930 | 01160 |
| Output | Rated motor <br> capacity ${ }^{(1)}$ <br> [kW] | 120\% overlaod capacity ${ }^{\text {(5) }}$ |  | 0.75 | 1.5 | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 |
|  |  | 150\% overlaod capacity |  | 0.75 | 1.5 | 2.2 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 |
|  | Rated current [A] ${ }^{6}$ | 120\% overlaod capacity ${ }^{(5)}$ | $\mathrm{I}_{\text {rated }}{ }^{\text {(6) }}$ | $\begin{aligned} & 2.3 \\ & (2.0) \end{aligned}$ | $\begin{aligned} & 3.8 \\ & (3.2) \end{aligned}$ | $\begin{aligned} & 5.2 \\ & (4.4) \end{aligned}$ | $\begin{aligned} & 8.3 \\ & (7.1) \end{aligned}$ | $\begin{aligned} & 12.6 \\ & (10.7) \end{aligned}$ | $\begin{aligned} & 17 \\ & (14.5) \end{aligned}$ | $\begin{aligned} & 25 \\ & (21.3) \end{aligned}$ | $\begin{aligned} & 31 \\ & (26.4) \end{aligned}$ | $\begin{aligned} & 38 \\ & (32.3) \end{aligned}$ | $\begin{aligned} & 47 \\ & (40.0) \end{aligned}$ | $\begin{aligned} & 62 \\ & (52.7) \end{aligned}$ | $\begin{aligned} & 77 \\ & (65.5) \end{aligned}$ | $\begin{aligned} & 93 \\ & (79.1) \end{aligned}$ | $\begin{aligned} & 116 \\ & (98.6) \end{aligned}$ |
|  |  |  | I max.60s | 2.5 | 4.2 | 5.7 | 9.1 | 13.9 | 18.7 | 27.5 | 34.1 | 41.8 | 51.7 | 68.2 | 84.7 | 102.3 | 127.5 |
|  |  |  | Imax.3s | 2.8 | 4.6 | 6.2 | 10 | 15.1 | 20.4 | 30 | 37.2 | 45.6 | 56.4 | 74.4 | 92.4 | 111.6 | 139.2 |
|  |  | 150\% overlaod capacity | $\mathrm{I}_{\text {rated }}{ }^{(6)}$ | $\begin{aligned} & 2.1 \\ & (1.8) \\ & \hline \end{aligned}$ | $\begin{aligned} & 3.5 \\ & (3.0) \end{aligned}$ | $\begin{aligned} & 4.8 \\ & (4.1) \end{aligned}$ | $\begin{aligned} & 7.6 \\ & (6.4) \end{aligned}$ | $\begin{aligned} & 11.5 \\ & (9.8) \end{aligned}$ | $\begin{aligned} & 16 \\ & \text { (13) } \end{aligned}$ | $\begin{aligned} & 23 \\ & \text { (19) } \end{aligned}$ | $\begin{aligned} & 29 \\ & (24) \end{aligned}$ | $\begin{aligned} & 35 \\ & (30) \end{aligned}$ | $\begin{aligned} & 43 \\ & (36) \\ & \hline \end{aligned}$ | $\begin{aligned} & 57 \\ & (48) \end{aligned}$ | $\begin{aligned} & 70 \\ & (60) \end{aligned}$ | $\begin{aligned} & 85 \\ & (72) \end{aligned}$ | $\begin{aligned} & 106 \\ & (90) \end{aligned}$ |
|  |  |  | Imax.60s | 2.5 | 4.2 | 5.8 | 9.1 | 13.8 | 19.2 | 27.6 | 34.8 | 42 | 51.6 | 68.4 | 84 | 102 | 127.2 |
|  |  |  | Imax.3s | 3.1 | 5.2 | 7.2 | 11.4 | 17.2 | 24 | 34.5 | 43.5 | 52.5 | 64.5 | 85.5 | 105 | 127.5 | 159 |
|  | Output capacity [kVA] | $120 \%$ overlaod capacity ${ }^{\text {(5) }}$ |  | 1.8 | 2.9 | 4.0 | 6.3 | 9.6 | 13 | 19.1 | 23.6 | 29.0 | 35.8 | 47.3 | 58.7 | 70.9 | 88.4 |
|  |  | 150\% overlaod capacity |  | 1.6 | 2.7 | 3.7 | 5.8 | 8.8 | 12.2 | 17.5 | 22.1 | 26.7 | 32.8 | 43.4 | 53.3 | 64.8 | 80.8 |
|  | Overload current rating ${ }^{(2)}$ | 120\% overlaod capacity |  | $120 \%$ of rated motor capacity for $3 \mathrm{~s} ; 1110 \%$ for 1 min. (max. ambient temperature $40^{\circ} \mathrm{C}$ ) - typical for pumps and fans |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 150\% overlaod capacity |  | $150 \%$ of rated motor capacity for $3 \mathrm{~s} ; 120 \%$ for 1 min. (max. ambient temperature $50^{\circ} \mathrm{C}$ ) - typical for conveyor belts and centrifuges |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Voltage ${ }^{(3)}$ |  |  | 3 -phase $\mathrm{AC}, \mathrm{OV}$ to power supply voltage |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Frequency range |  |  | $0.5-400 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Control method |  |  | V/f control, optimum excitation control or simple magnetic flux vector control |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Modulation control |  |  | Sine evaluated PWM, Soft PWM |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Carrier frequency |  |  | $0.7 \mathrm{kHz}-14.5 \mathrm{kHz}$ (user adjustable) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Input | Power supply voltage |  |  | 3-phase, 380-480 V AC, $-15 \% /+10 \%$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Voltage range |  |  | $323-528 \mathrm{~V} \mathrm{AC} \mathrm{at} 50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Power supply frequency |  |  | $50 / 60 \mathrm{~Hz} \pm 5 \%$ |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Rated input capacity ${ }^{4}$ [kVA] | $120 \%$ overlaod capacity (5) |  | 2.8 | 5.0 | 6.1 | 10 | 13 | 19 | 22 | 31 | 37 | 45 | 57 | 73 | 88 | 110 |
|  |  | 150\% overlaod capacity |  | $\begin{array}{lll}2.5 & 4.5\end{array}$ |  |  | 9 | 12 | 17 | 20 | 28 | 34 | 41 | 52 | 66 | 80 | 100 |
| Others | Cooling |  |  | Self cooling |  |  | Fan cooling |  |  |  |  |  |  |  |  |  |  |
|  | Power loss [kW] | 120\% overlaod capacity ${ }^{(5)}$ |  | 0.06 | 0.08 | 0.1 | 0.16 | 0.19 | 0.24 | 0.34 | 0.39 | 0.49 | 0.58 | 0.81 | 1.0 | 1.17 | 1.51 |
|  |  | 150\% overlaod capacity |  | 0.05 | 0.08 | 0.09 | 0.14 | 0.18 | 0.22 | 0.31 | 0.35 | 0.44 | 0.52 | 0.71 | 0.93 | 1.03 | 1.32 |
|  | Frame size |  |  | C |  |  |  |  | D |  | E |  | F |  | G | H |  |
|  | Inverter weight [kg] |  |  | 3.5 | 3.5 | 3.5 | 3.5 | 3.5 | 6.5 | 6.5 | 7.5 | 7.5 | 13 | 13 | 23 | 35 | 35 |
|  | Reactor weight [kg] |  |  | - | - | - | - | - | - | - | - | - | - | - | - | - | - |
| Order information (8) |  |  | Order no. | 156569 | 156570 | 156571 | 156572 | 156573 | 156594 | 156595 | 156596 | 156597 | 156598 | 156599 | 156600 | 156601 | 156602 |

(1) The performance figures at the rated motor capacity are based on a motor voltage of 400 V .
(2) The overload capacity in \% is the ratio of the overload current to the inverter's rated current in the respective operating mode. For repeated duty cycles allow sufficient time for the inverter and the motor to cool below the temperature reached at $100 \%$ load. The waiting periods can be calculated using the r.m.s. current method $\left(1^{2} \times t\right)$, for which knowledge of the duty.
(3) The maximum output voltage cannot exceed the power supply voltage. The output voltage can be varied over the entire power supply voltage range.
(4) The rated input capacity varies depending on the impedance values on the power supply side of the inverter (including the cables and input reactor).
(5) When the load curve with $120 \%$ overload capacity is selected the maximum permitted ambient temperature is $40^{\circ} \mathrm{C}$.
(6) When operating with carrier frequencies $\geq 3 \mathrm{kHz}$ this value is reduced automatically as soon as the frequency inverter exceeds the rated output current shown in parentheses ( $=85 \%$ load).
(7) When the cable bushing for the optional expansion cards is broken out the unit has an IP 00 protection rating.
(8) The suffix EC or E1 in the model designation identifies the CE versions of the frequency inverter (for the European Union). The inverter types FR-F740-02160 and above are all delivered in the E1 version as standard (PCBs with two coats of protective varnish). The EC version (varnished PCBs) is standard for types FR-F740 00023 through 01800. The other version as always available as an option.

## Specifications FR-F 740-01800 to -12120

| Series |  |  |  | FR-F740 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  | 01800 | 02160 | 02600 | 03250 | 03610 | 04320 | 04810 | 05470 | 06100 | 06830 | 07700 | 08660 | 09620 | 10940 | 12120 |  |
| Output | Rated motor <br> capacity ${ }^{(1)}$ <br> [kW] | 120\% overlaod capacity (5) |  | 90 | 110 | 132 | 160 | 185 | 220 | 250 | 280 | 315 | 355 | 400 | 450 | 500 | 560 | 630 |  |
|  |  | 150\% overlaod capacity |  | 75 | 90 | 110 | 132 | 160 | 185 | 220 | 250 | 280 | 315 | 355 | 400 | 450 | 500 | 560 |  |
|  | Rated current <br> $[\mathrm{A}]^{(6)}$ | 120\% overlaod capacity (5) | $\mathrm{I}_{\text {rated }}{ }^{\text {(6) }}$ | $\begin{aligned} & 180 \\ & (153) \end{aligned}$ | $\begin{aligned} & 216 \\ & (184) \end{aligned}$ | $\begin{aligned} & 260 \\ & (221) \end{aligned}$ | $\begin{aligned} & 325 \\ & (276) \end{aligned}$ | $\begin{aligned} & 361 \\ & (307) \end{aligned}$ | $\begin{aligned} & 432 \\ & (367) \end{aligned}$ | $\begin{aligned} & 481 \\ & (409) \end{aligned}$ | $\begin{aligned} & 547 \\ & (465) \end{aligned}$ | $\begin{aligned} & 610 \\ & (518) \end{aligned}$ | $\begin{aligned} & 683 \\ & (581) \end{aligned}$ | $\begin{aligned} & 770 \\ & (654) \end{aligned}$ | $\begin{aligned} & 866 \\ & (736) \end{aligned}$ | $\begin{aligned} & 962 \\ & (818) \end{aligned}$ | $\begin{aligned} & 1094 \\ & (870) \end{aligned}$ | $\begin{aligned} & 1212 \\ & (1030) \end{aligned}$ |  |
|  |  |  | Imax. 60 s | 198 | 238 | 286 | 357 | 397 | 475 | 529 | 602 | 671 | 751 | 847 | 953 | 1058 | 1203 | 1333 |  |
|  |  |  | Imax.3s | 216 | 259 | 312 | 390 | 433 | 518 | 577 | 656 | 732 | 820 | 924 | 1039 | 1154 | 1313 | 1454 |  |
|  |  | 150\% overlaod capacity | $\mathrm{I}_{\text {rated }}{ }^{(6)}$ | $\begin{aligned} & 144 \\ & (122) \end{aligned}$ | $\begin{aligned} & 180 \\ & (153) \end{aligned}$ | $\begin{aligned} & 216 \\ & (184) \end{aligned}$ | $\begin{aligned} & 260 \\ & (221) \end{aligned}$ | $\begin{aligned} & 325 \\ & (776) \end{aligned}$ | $\begin{aligned} & 361 \\ & (307) \end{aligned}$ | $\begin{aligned} & 432 \\ & (367) \end{aligned}$ | $\begin{aligned} & 481 \\ & (409) \end{aligned}$ | $\begin{aligned} & 547 \\ & (465) \end{aligned}$ | $\begin{aligned} & 610 \\ & (518) \end{aligned}$ | $\begin{aligned} & 683 \\ & (581) \end{aligned}$ | $\begin{aligned} & 770 \\ & (654) \end{aligned}$ | $\begin{aligned} & 866 \\ & (736) \end{aligned}$ | $\begin{aligned} & 962 \\ & (818) \end{aligned}$ | $\begin{aligned} & 1094 \\ & (870) \end{aligned}$ |  |
|  |  |  | I max. 60 s | 173 | 216 | 259 | 312 | 390 | 433 | 518 | 577 | 656 | 732 | 820 | 924 | 1039 | 1154 | 1313 |  |
|  |  |  | Imax.3s | 216 | 270 | 324 | 390 | 487 | 541 | 648 | 721 | 820 | 915 | 1024 | 1155 | 1299 | 1443 | 1641 |  |
|  | Output capacity [kVA] | 120\% overlaod capacity ${ }^{(5)}$ |  | 137 | 165 | 198 | 248 | 275 | 329 | 367 | 417 | 465 | 521 | 587 | 660 | 733 | 834 | 924 |  |
|  |  | 150\% overlaod capacity |  | 110 | 137 | 165 | 198 | 248 | 275 | 329 | 367 | 417 | 465 | 521 | 587 | 660 | 733 | 834 |  |
|  | Overload current rating ${ }^{(2)}$ | 120\% overlaod capacity |  | $120 \%$ of rated motor capacity for $3 \mathrm{~s} ; 110 \%$ for 1 min. (max. ambient temperature $40^{\circ} \mathrm{C}$ ) - typical for pumps and fans |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  |  | 150\% overlaod capacity |  | $150 \%$ of rated motor capacity for 3 ; $120 \%$ for 1 min. (max. ambient temperature $50^{\circ} \mathrm{C}$ ) - typical for conveyor belts and centrifuges |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Voltage ${ }^{3}$ |  |  | 3 -phase $A C, O \mathrm{~V}$ to power supply voltage |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Frequency range |  |  | $0.5-400 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Control method |  |  | V/f control, optimum excitation control or simple magnetic flux vector control |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Modulation control |  |  | Sine evaluated PWM, Soft PWM |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Carrier frequency |  |  | $0.7 \mathrm{kHz}-6 \mathrm{kHz}$ (user adjustable) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Input | Power supply voltage |  |  | 3-phase, 380-500 V AC, -15\% / + 10\% |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Voltage range |  |  | $323-550 \mathrm{~V} \mathrm{AC} \mathrm{at} 50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Power supply frequency |  |  | $50 / 60 \mathrm{~Hz} \pm 5 \%$ |  |  |  |  |  |  |  |  |  |  |  |  |  |  | \% |
|  | Rated input capacity ${ }^{4}$ [kVA] | $120 \%$ overlaod capacity ${ }^{\text {(5) }}$ |  | 137 | 165 | 198 | 248 | 275 | 329 | 367 | 417 | 465 | 520 | 587 | 660 | 733 | 834 | 924 |  |
|  |  | 150\% overlaod capacity |  |  | 137 | 165 | 198 | 248 | 275 | 329 | 367 | 417 | 465 | 520 | 587 | 660 | 733 | 834 |  |
| Others | Cooling |  |  | Fan cooling |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | Power loss [kW] | 120\% overlaod capacity ${ }^{(5)}$ |  | 2.7 | 3.3 | 3.96 | 4.8 | 5.55 | 6.6 | 7.5 | 8.4 | 9.45 | 10.65 | 12.0 | 13.5 | 15.0 | 16.8 | 18.9 |  |
|  |  | 150\% overlaod capacity |  | 2.25 | 2.7 | 3.3 | 3.96 | 4.8 | 5.55 | 6.6 | 7.5 | 8.4 | 9.45 | 10.65 | 12.0 | 13.5 | 15.0 | 16.8 |  |
|  | Frame size |  |  | H | J |  | K |  | L |  | M |  |  | N |  | P |  |  | $11$ |
|  | Inverter weight [kg] |  |  | 37 | 50 | 57 | 72 | 72 | 110 | 110 | 220 | 220 | 220 | 235 | 235 | 285 | 285 | 285 |  |
|  | Reactor weight [kg] |  |  | 20 | 22 | 26 | 28 | 29 | 30 | 35 | 38 | 42 | 46 | 50 | 57 | 67 | 85 | 95 | 完 |


| Order information (8) | Order no. | 158604 | 158605 | 158607 | 158608 | 158609 | 158610 | 158611 | 158612 | 158613 | 158614 | 158615 | 158616 | 158617 | 158619 | 158620 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

(1) The performance figures at the rated motor capacity are based on a motor voltage of 400 V .
(2) The overload capacity in \% is the ratio of the overload current to the inverter's rated current in the respective operating mode. For repeated duty cycles allow sufficient time for the inverter and the motor to cool below the temperature reached at $100 \%$ load. The waiting periods can be calculated using the r.m.s. current method ( $\left.1^{2} \times \mathrm{t}\right)$, for which knowledge of the duty.
(3) The maximum output voltage cannot exceed the power supply voltage. The output voltage can be varied over the entire power supply voltage range.
(4) The rated input capacity varies depending on the impedance values on the power supply side of the inverter (including the cables and input reactor).
(5) When the load curve with $120 \%$ overload capacity is selected the maximum permitted ambient temperature is $40^{\circ} \mathrm{C}$.
(6) When operating with carrier frequencies $\geq 2.5 \mathrm{kHz}$ this value is reduced automatically as soon as the frequency inverter exceeds the rated output current shown in parentheses ( $=85 \%$ load).
(7) When the cable bushing for the optional expansion cards is broken out the unit has an IP 00 protection rating.
(8) The suffix EC or E1 in the model designation identifies the CE versions of the frequency inverter (for the European Union). The inverter types FR-F740-02160 and above are all delivered in the E1 version as standard (PCBs with two coats of protective varnish). The EC version (varnished PCBs) is standard for types FR-F740 00023 through 01800. The other version as always available as an option.

## Specifications

| FR-F740 |  |  | Description |
| :---: | :---: | :---: | :---: |
| Control specifications | Frequency setting resolution | Analog input | $0.015 \mathrm{~Hz} / 0-50 \mathrm{~Hz}$ (terminal 2,4:0-10 V/12 bit) <br> $0.03 \mathrm{~Hz} / 0-50 \mathrm{~Hz} /($ terminal $2,4: 0-5 \mathrm{~V} / 11$ bit, $0-20 \mathrm{~mA} / 11$ bit, terminal $1:-10-+10 \mathrm{~V} / 11 \mathrm{bit})$ $0.06 \mathrm{~Hz} / 0-50 \mathrm{~Hz}$ (terminal 1:0 $- \pm 5 \mathrm{~V} / 10$ bit) |
|  |  | Digital input | 0.01 Hz |
|  | Frequency accuracy |  | $\pm 0.2 \%$ of the maximum output frequency (temperature range $25^{\circ} \pm 10^{\circ} \mathrm{C}$ ) via analog input; $\pm 0.01 \%$ of the set output frequency (via digital input) |
|  | Voltage / frequency characteristics |  | Base frequency adjustable from 0 to 400 Hz ; selection between constant torque, variable torque or optional flexible 5 -point V/f characteristics |
|  | Starting torque |  | $120 \%(3 \mathrm{~Hz})$ when set to simple magnetic flux vector control and slip compensation |
|  | Acceleration / deceleration time |  | $0 ; 0.1$ to 3600 s (can be set individually) |
|  | Acceleration / deceleration characteristics |  | Linear or S-form course, user selectable |
|  | DC injection brake |  | Operating frequency ( $0-120 \mathrm{~Hz}$ ), operating time ( $0-10 \mathrm{~s}$ ) and operating voltage ( $0-30 \%$ ) can be set individually. The $D C$ brake can also be activated via the digital input. |
|  | Stall prevention |  | Respones threshold 0-150\%, user adjustable, also via analog input |
|  | Motor protection |  | Electronic motor protection relay (rated current user adjustable) |
| Control signals for operation | Frequency setting values | Analog input | Terminal 2, 4: 0-5 V DC, $0-10 \mathrm{~V} D \mathrm{DC}, 0 / 4-20 \mathrm{~mA}$ Terminal 1:0- $\pm 5 \mathrm{VDC}, 0- \pm 10 \mathrm{VDC}$ |
|  |  | Digital input | Operation panel or optional expansion board |
|  | Start signal |  | Available individually for forward rotation and reverse rotation. Start signal automatic self-holding input (3-wire input) can be selected. |
|  | Input signals |  | Any of 12 signals can be selected using parameters 178 to 189 (input terminal function selection): <br> multi speed, second parameter function, terminal 4 input, JOG operation, automatic restart after instantaneous power failure, external thermal relay input, FR-HC connection (inverter operation enable signal) and FR-HC connection (instantaneous power failure detection), control panel operation/external interlock signal, PID control, control panel operation, control panel<->external operation, output stop, start self-holding, forward/reverse rotation command, inverter reset, PTC thermistor input, PID forward/reverse operation switchover, control panel<->NET,NET<->external operation, command source switchover |
|  | Output signals | Operating state | Any of 7 signals can be selected using parameter 190 to 196 (output terminal function selection): <br> Frequency control status, instantaneous power failure (under voltage), overload warning, output frequency detection, second output frequency detection, regenerative brake with pre-alarm ( 01800 and above), electronic thermal relay function with pre-alarm, control panel operation mode, inverter operation ready, output current detection, zero current detection, PID lower limit, PID upper limit, PID forward rotation/reverse rotation, commercial power supply-inverter switchover, direct mains operation motor 1-4, frequency inverter operation motor 1-4, inverter running start command ON, deceleration at an instantaneous power failure, PID control activated, re-start, PID output suspension, life time alarm, alarm output 3 ( $O$ FF signal), power savings average value update timing, current average monitor, alarm output2, maintenance timer alarm, remote outputs, minor failure output, alarm output, traverse operation, open-collector outputs ( 5 outputs), relay outputs (2 outputs), alarm code outputs (4 bits via open-collector) |
|  |  | When using the FR-A7AY option | In addition to the above operating modes parameters 313-319 (function selection for the additional 7 output terminals) can also be used to assign the following four signals: control circuit capacitor life, main circuit capacitor life, cooling fan life, inrush current limit circuit life |
|  |  | Pulse/analog output | You can also use parameter 54 (assign analog current output) and 158 (assign analog voltage output) to assign the following displays to one or both outputs: <br> output frequnecy, motor current (steady or peak), output voltage, frequency setting value, motor running speed, converter output voltage (steady or peak), electronic thermal relay function load factor, input voltage, output voltage, load meter, reference voltage output, motor load factor, energy saving effect, regenerative brake circuit duty ( 01800 and above), PID set point, PID process value |
| Display | Control unit display (FR-PU04/ FR-DU07) | Operating state | Output frequency, motor current (steady or peak value), output voltage, alarm indication, frequency setting, motor running speed, converter output voltage (steady or peak value), electronic thermal load factor, input power, output power, road meter, cumulative energization time, actual operation time, motor load factor, watt-hours meter, power saving effect, cumulative saving power, regenerative brake circuit duty ( 01800 and above), PID set point, PID process value, PID deviation monitor, //0 terminal monitor, optional input terminal monitor (FR-DU07 only), optional output terminal monitor (FR-DU07 only), option fitting state monitor (FR-PU04 only), terminal assignment state (FR-PU04 only) |
|  |  | Alarm definition | Alarm definition is displayed when the protective function is activated, the output voltage/current/frequency/cumulative energization time right before the protection function was activated and the past 8 alarm definitions are stored. |
|  |  | Interactive guidance | Operation guide/trouble shooting with a help function (FR-PU04 only) |
| Protection | Protective functions |  | Overcurrent cutoff (during acceleration, deceleration or at constant speed), overvoltage cutoff (during acceleration, deceleration or at constant speed), inverter protection thermal operation, motor protection thermal operation, heatsink overheat, instantaneous power failure occurence, under voltage, input phase failure, motor overload, output short circuit, ground fault overcurrent, output phase failure, external thermal relay operation, PTC thermistor operation, option alarm, parameter error, control unit disconnection, retry count excess, CPU alarm, power supply short for control panel, 24 V D power output short, output current detection value over, inrush resitance overheat, communication error (frequency inverter), analog input alarm, internal circuit alarm ( 15 V D ( power supply), fan fault, overcurrent stall prevention, overvoltage stall prevention, electronic thermal pre-alarm, control unit stop, maintenance timer alarm (FR-DU07 only),MT-BU5 external brake module overload ( 01800 and above), parameter write error, copy error, operation panel lock, parameter copy error |
|  | Protection rating* |  | IP20 (FR-F 740-00023 to -00620); <br> IPOO (FR-F 740-00770 to -12120) |

* FR-DU07: IP40 (does not apply for the PU connection)


## General Operating Conditions

| Item | Specifications |
| :---: | :---: |
| Ambient temperature in operation | $-10^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$（non－freezing） <br> For selection of the load characteristics with a $120 \%$ overload rating the max．temperature is $40^{\circ} \mathrm{C}$ ． |
| Storage temperature＊ | -20 to $+65^{\circ} \mathrm{C}$ |
| Ambient humidity | Max．90\％RH（non－condensing） |
| Altitude | Max． 1000 m above NN |
| Shock resistance | 10 G （3 times each in 3 directions） |
| Vibration resistance | Max． 0.6 G |
| Ambience conditions | For indoor use only，avoid environments containing corrosive gases，install in a dust－free location． |
| Certifications | UL／CSA／CE／EN／Gost／CCC |
| Max．cable length | 2 kHz ：up to 300 m for 0023 ，other types up to 500 m ＜ 5 kHz ：up to 200 m for 0023 ，up to 300 m for 0038，other types up to 500 m $5-9 \mathrm{kHz}$ ：up to 100 m <br> $\geq 10 \mathrm{kHz}$ ：up to 50 m |


＊The product may only be exposed to the full extremes of this temperature range for short periods（e．g．during transportation）．

Block Diagram


## Terminal Assignment of Main Circuit Terminals

| Function | Terminal | Designation | Description |
| :---: | :---: | :---: | :---: |
| Main circuit connection | L1, L2, L3 | Mains supply connection | Mains power supply of the inverters ( $380-480 \mathrm{~V} \mathrm{AC}, 50 / 60 \mathrm{~Hz}$ ); ( $380-500 \mathrm{~V}-01800$ and above) |
|  | P/+, N/- | External brake unit connection | An optional external brake resistor can be connected to the terminals P and N or you can connect a optional high power factor converter. |
|  | P1, P/+ | Converter choke coil connection | An optional choke coil can be connected to the terminals P1 and P/+. The jumper on terminals P1 and P/+ must be removed when this optional choke coil is used on frequency inverter models 01160 and below. The $D C$ reactor supplied with the unit must be installed on frequency inverter models 01800 and above. |
|  | PR, PX |  | Please do not remove or use terminals PR and PX or the jumper connected. |
|  | $\mathrm{U}, \mathrm{V}, \mathrm{W}$ | Motor connection | Voltage output of the inverter (3-phase, 0 V up to power supply voltage, $0,5-400 \mathrm{~Hz}$ ) |
|  | L11, L21 | Control circuit mains supply connection | To use external power for the control circuit connect the mains power to L11/L21 (and remove jumpers L 1 and L 2 ). |
|  | CN8 | Ext. brake transistor control | Control connection for the MT-BU5 external brake module |
|  | $\stackrel{1}{ \pm}$ | PE | Protective earth connection of inverter |

## Terminal Assignment of Signal Terminals

| Function | Terminal | Designation | Description |
| :---: | :---: | :---: | :---: |
| Control connection (programmable) | STF | Forward rotation start | The motor rotates forward, if a signal is applied to terminal STF. |
|  | STR | Reverse rotation start | The motor rotates reverse, if a signal is applied to terminal STR. |
|  | STOP | Start self-retaining selection | The start signals are self-retaining, if a signal is applied to terminal STOP. |
|  | RH, RM, RL | Multi-speed selection | Preset of 15 different output frequencies |
|  | JOG | Jog mode selection | The JOG mode is selected, if a signal is applied to terminal JOG (factory setting). The inverters FR-A 540L-G 375 k and 450 k are not equipped with a JOG terminal. The start signals STF and STR determine the rotation direction. |
|  | RT | Second parameter settings | A second set of parameter settings is selected, if a signal is applied to terminal RT. |
|  | MRS | Output stop | The inverter lock stops the output frequency without regard to the delay time. You can select a make or break signal for the controller inhibit function by changing parameter 17. |
|  | RES | RESET input | An activated protective circuit is reset, if a signal is applied to the terminal RES ( $\mathrm{t}>0,1 \mathrm{~s}$ ). |
|  |  | Current input selection | The 0/4-20mA signal on terminal 4 is enabled by a signal on the AU terminal. |
|  | AU | PTC input | If you connect a PTC temperature sensor you must assign the PTC signal to the AU terminal and set the slide switch on the control circuit board to the PTC position. |
|  | CS | Automatic restart after instantaneous power failure | The inverter restarts automatically after a power failure, if a signal is applied to the terminal CS . |
| Common | SD | Reference potential (OV) for the PC terminal (24V) | When "sink" control logic is selected by setting the control signal jumper a specific control function is triggered when the corresponding control terminal is connected to the SD terminal. <br> When "source" control logic is selected and you are using external 24V power you must connect the OV of the external power supply to terminal SD. The SD terminal is isolated from the digital electronics with optocouplers. |
|  | PC | 24 V DC output | Internal power supply 24 V DC/0,1 A output |
| Setting value specification | 10 E | Voltage output for potentiometer | Output voltage 10 VDC . <br> Max. output current 10 mA . <br> Recommended potentiometer: $1 \mathrm{k} \Omega, 2 \mathrm{~W}$ linear |
|  | 10 |  | Output voltage 5 V DC. <br> Max. output current 10 mA . <br> Recommended potentiometer: $1 \mathrm{k} \Omega, 2 \mathrm{~W}$ linear |
|  | 2 | Input for frequency setting value signal | The setting value $0-10 \mathrm{~V}$ or $0 / 4-20 \mathrm{~mA}$ is applied to this terminal. You can switch between voltage and current setpoint values with parameter 73 . The input resistance is $10 \mathrm{k} \Omega$. |
|  | 5 | Reference point for frequency setting value signal | Terminal 5 is the reference point for all analog setting values and for the analog output signal AM and CA. The terminal is not isolated from the reference potential of the control circuit and must not be earthed. |
|  | 1 | Auxiliary input for frequency setting value signal $0- \pm 5$ (10) VDC | An additional voltage setting value signal of $0- \pm 5(10) V D C$ can be applied to terminal 1 . The voltage range is preset to $0- \pm 10 \mathrm{~V} D$. The input resistance is $10 \mathrm{k} \Omega$. |
|  | 4 | Input for setting value signal | The setting value $0 / 4-20 \mathrm{~mA}$ or $0-10 \mathrm{~V}$ is applied to this terminal. You can switch between voltage and current setpoint values with parameter 73 . The input resistance is $250 \Omega$. <br> The current setting value is enabled via terminal function AU. |
| Signal output (programmable) | A1, B1, C1 | Potential free <br> Relay output 1 (Alarm) | The alarm is output via relay contacts. The block diagram shows the normal operation and voltage free status. If the protective function is activated, the relay picks up. The maximum contact load is $200 \mathrm{~V} \mathrm{AC} / 0.3 \mathrm{~A}$ or $30 \mathrm{~V} \mathrm{DC} / 0.3 \mathrm{~A}$. |
|  | A2, B2, C2 | Potential free Relay output 2 | Any of the available 42 output signals can be used as the output driver. The maximum contact load is $230 \mathrm{~V} \mathrm{AC} / 0.3 \mathrm{~A}$ oder $30 \mathrm{~V} \mathrm{DC} / 0.3 \mathrm{~A}$. |
|  | RUN | Signal output for motor operation | The output is switched low, if the inverter output frequency is equal to or higher than the starting frequency. The output is switched high, if no frequency is output or the DC brake is in operation. |
|  | SU | Signal output for frequency setting value/current value comparison | The SU output supports a monitoring of frequency setting value and frequency current value. The output is switched low, once the frequency current value (output frequency of the inverter) approaches the frequency setting value (determined by the setting value signal) within a preset range of tolerance. |
|  | IPF | Signal output for instantaneous power failure | The output is switched low for a temporary power failure within a range of $15 \mathrm{~ms} \leq \mathrm{t}_{\text {IPF }} \leq 100 \mathrm{~ms}$ or for under voltage. |
|  | OL | Signal output for overload alarm | The $0 L$ is switched low, if the output current of the inverter exceeds the current limit preset in parameter 22 and the stall prevention is activated. If the output current of the inverter falls below the current limit preset in parameter 22, the signal at the OL output is switched high. |
|  | FU | Signal output for monitoring output frequency | The output is switched low once the output frequency exceeds a value preset in parameter 42 (or 43). Otherwise the FU output is switched high. |
|  | SE | Reference potential for signal outputs | The potential that is switched via open collector outputs RUN, SU, OL, IPF and FU is connected to this terminal. |
|  | CA | Current output 0-20 mA | One of 18 monitoring functions can be selected, e.g.external frequency output. CA and AM output can be used simultaneously. The functions are determined by parameters. <br> An amperemeter can be connected (measuring range: $0-20 \mathrm{~mA}$ ). |
|  | AM | $\begin{aligned} & \text { Analog output } 0-10 \mathrm{~V} \\ & (1 \mathrm{~mA}) \end{aligned}$ | One of 18 monitoring functions can be selected, e.g.external frequency output. CA and AM output can be used simultaneously. The functions are determined by parameters. <br> A DC voltmeter can be connected. The max. output voltage is 10 V . |
| Interface | - | Connection of control panel (via RS485 terminal) | Communications via RS485 <br> I/0 standard: RS 485 ,Multi-Drop operation, 4,800 - 38,400 Baud (overall length: 500 m ) |
|  | - | RS484 terminal (via RS485 terminal) | Communications via RS485 <br> I/O standard: RS485,Multi-Drop operation, 300 - 38,400 Baud (overall length: 500 m ) |

## Built－in Operation Panel FR－DU07（Standard）



Setting monitoring and frequency


## Setting parameters



## Control Panel FR-PU04 (Option)

The control panel FR-PU04 with extended functions is available as optional accessory. This control panel provides a 10-key keypad for a direct entering of numerical values. A 4-row LC display returns operational data, parameter names or status and error messages in uncoded text. The control panel displays text in the following selectable languages: English, German, French, Spanish, Swedish, Italian, Finnish, and Japanese. In addition to the functions* of the standard control panel the FR-PU04 displays and monitors 21 different values and states in total.
The control unit FR-PU04 is used instead of the standard control unit FR-DU04 and can be replaced by this after use.

[^0]

## Menu Guide to the Control Panel FR-PU04

## Displaying the parameter list

Press the SET key to enter the parameter setting menu. Then press the HELP key to display the parameter lists. After pressing the READ key, the according parameter value will be read in.

## Copying parameters

Press the SET key and then the $\boldsymbol{\Delta}$ key to enter the copy mode. Now you find three choices:

- Press the READ key to read out all parameters from the inverter.
- Press the WRITE key to write parameters to the inverter.
- Press the $\boldsymbol{\nabla}$ key to verify the values stored in the control panel and the inverter.



## Operating Modes

The inverter can alternatively be operated via external signals or directly via the ope－ ration panel FR－DU07 or the control panels FR－PU04．
On the FR－DU07 control panel the opera－ ting mode is selected by pressing the PU／EXT key．On the FR－PU04 the EXT key selects operation by external signals and the PU key selects operation via the control panel．

## Operation from the control panel

The direction of rotation and frequency setting of the inverter are controlled from the built－in operation panel．
The setting of the output frequency is increased or decreased via the Digital Dial．


## Operation by external signals

The direction of rotation and frequency setting of the inverter are controlled by external signals．The following figure shows the display on the built－in operation panel FR－DU07 for forward rota－ tion of the motor and a frequency of 50 Hz ．


## Combined operation

In addition to the operation by external signals and the operation from the control panel（built－in or external）the inverter can be operated in combined operation mode．
－Setting value preset from the control panel and external starting signal．
－External setting value signal and star－ ting signal from the control panel．
（5）Stop motor


## VFD Setup Software

The VFD Setup Software is a powerful tool for the operation of your frequency inverter. The software (version 2.4) is MS Windows 95/98/ME/XP and NT/2000 compatible, and therefore allows the inverter operation via any conventional personal computer. Several frequency inverters can be set up, operated, and monitored simultaneously across a network or via a personal computer or notebook. The software is designed for all frequency inverters of the MITSUBISHI FR-S 500, FR-E 500, FR-A 500, FR-F 500 and FR-F 700* series.
The connection between personal computer and inverter is established either via an RS485 network or directly via an SC-FR PC adapter cable available separately.


## Benefits

- System settings

Due to the network capabilities of the inverter up to 32 frequency inverters can be operated simultaneously.

- Parameter settings

By means of overall and function related overviews different parameters can be adjusted easily.

- Display functions

The comprehensible display functions enable data, analog, oscillograph, and alarm displays.

- Diagnostis

The analysis of the inverter status provides a thorough error correction.

- Test operation

The test operation provides a simulation of the operation and adjustment via the auto-tuning function.

- File management

Parameters can be saved on the personal computer and printed out.

- Help

The extensive online help provides support concerning all questions regarding settings and operation.

Parameter setting


Display and monitor


Test operation


[^1]Parameter Overview


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Display functions | 52 | DU/PU main display data selection ${ }^{(1)}$ | $\begin{gathered} 0 / 5 / 6 / 8-14 / 17 / 20 / 23 / \\ 24 / 25 / 50-57 / 100{ }^{(3)} \end{gathered}$ | 0 |
|  | 54 | CA terminal function selection ${ }^{(1)}$ | 1-3/5/6/8-14/17/21/24/50/52/53 3 | 1 |
|  | 55 | Frequency monitoring reference ${ }^{(1)}$ | $0-400 \mathrm{~Hz}$ | 50 Hz |
|  | 56 | Current monitoring reference ${ }^{(1)}$ | $\begin{gathered} 0-500 \mathrm{~A} \\ 0-3600 \mathrm{~A}^{(2} \end{gathered}$ | Rated current |
| Restart | 57 | Restart coasting time | $\begin{aligned} & 0 / 0.1-5 \mathrm{~s} / 9999 / \\ & 0 / 0.1-30 \mathrm{~s} / 9999 \end{aligned}$ | 9999 |
|  | 58 | Restart cushion time | 0-60s | 1 s |
| Aux. functions | 59 | Remote function selection | 0/1/2/3 | 0 |
| Operation settings | 60 | Energy saving control selection | 0/4/9 | 0 |
|  | 65 | Retry selection | 0-5 | 0 |
|  | 66 | Stall prevention operation reduction starting frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
|  | 67 | Number of retries at alarm occurrence | 0-10/101-110 | 0 |
|  | 68 | Retry waiting time | 0-10s | 1 s |
|  | 69 | Retry count display erase | 0 | 0 |
|  | 70 | Special regenerative brake duty ${ }^{(4)}$ | 0-10\% | 0\% |
|  | 71 | Applied motor | 0/1/2/20 | 0 |
|  | 72 | PWM frequency selection ${ }^{(1)}$ | $\begin{gathered} 0-15 / \\ 0-6 / 25 \end{gathered}$ | 2 |
|  | 73 | Analog input selection | 0-7/10-17 | 1 |
|  | 74 | Input filter time constant | 0-8 | 1 |
|  | 75 | Reset selection/disconnected PU detection/PU stop selection ${ }^{(1)}$ | 0-3/14-17/100-103/114-117 ${ }^{\text {⑤ }}$ | 14 |
|  | 76 | Alarm code output selection | 0/1/2 | 0 |
|  | 77 | Parameter write selection ${ }^{(1)}$ | 0/1/2 | 0 |
|  | 78 | Reverse rotation prevention selection | 0/1/2 | 0 |
|  | 79 | Operation mode selection | 0-4/6/7 | 0 |
| Simple magnetic flux vector control | 80 | Motor capacity (simple magnetic flux vector control) | $\begin{gathered} 0.4-55 \mathrm{~kW} / 9999 / \\ 0-3600 \mathrm{~kW} / 9999{ }^{2} 2 \end{gathered}$ | 9999 |
|  | 90 | Motor constant (R1) | $\begin{gathered} 0.4-50 \Omega / 9999 / \\ 0-400 \mathrm{~m} \Omega / 9999{ }^{2} \end{gathered}$ | 9999 |
| Multi-speed setting | 100 | V/f1 (1st frequency) | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 101 | V/f1 (1st frequency voltage) | 0-1000 V | 0 |
|  | 102 | V/f2 (2nd frequency) | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 103 | V/f2 (2nd frequency voltage) | 0-1000 V | 0 |
|  | 104 | V/f3 (3rd frequency) | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 105 | V/f3 (3rd frequency voltage) | 0-1000 V | 0 |
|  | 106 | V/f4 (4th frequency) | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 107 | V/f4 (4th frequency voltage) | 0-1000 V | 0 |
|  | 108 | V/f5 (5th frequency) | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 109 | V/f5 (5th frequency voltage) | $0-1000 \mathrm{~V}$ | 0 |
| Communication functions | 117 | PU communication station | 0-31 | 0 |
|  | 118 | PU communication speed | 48/96 / 192 / 384 | 192 |
|  | 119 | PU communication stop bit length | $0 / 1$ data length $8 ; 10 / 11$ data lengthe 7 | 1 |
|  | 120 | PU communication parity check | 0/1/2 | 2 |
|  | 121 | Number of PU communication retries | 0-10/9999 | 1 |
|  | 122 | PU communication check time interval | 0-999.8 s / 9999 | 9999 |
|  | 123 | PU communication waiting time setting | 0-150 ms/9999 | 9999 |
|  | 124 | PU communication CR/LF presence/absence selection | 0/1/2 | 1 |
|  | 125 | Terminal 2 frequency setting gain frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
|  | 126 | Terminal 4 frequency setting gain frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
| PID control | 127 | PID control automatic switchover frequency | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 128 | PID action selection | 10/11/20/21/50/51/60/61 | 10 |
|  | 129 | PID proportional band (1) | 0.1-1000\% / 9999 | 100\% |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| PID control | 130 | PID integral time ${ }^{(1)}$ | 0.1-3600 s / 9999 | 1 s |
|  | 131 | PID upper limit | 0-100\% / 9999 | 9999 |
|  | 132 | PID lower limit | 0-100\% / 9999 | 9999 |
|  | 133 | PID action set point ${ }^{(1)}$ | 0-100\% | 0\% |
|  | 134 | PID differential time ${ }^{(1)}$ | 0.01-10.00 s / 9999 | 9999 |
| Commercial power supply switch-over | 135 | Power-supply switchover sequence output terminal selection | $0 / 1$ | 0 |
|  | 136 | MC switchover interlock time | 0-100 s | 1 s |
|  | 137 | Waiting time at a start | $0-100 \mathrm{~s}$ | 0.5 s |
|  | 138 | Commercial power-supply operation switchover selection at an alarm | $0 / 1$ | 0 |
|  | 139 | Automatic switchover frequency between inverter and commercial power-supply operation | 0-60 Hz / 9999 | 9999 |
| Backlash | 140 | Backlash acceleration stopping frequency | $0-400 \mathrm{~Hz}$ | 1 Hz |
|  | 141 | Backlash acceleration stopping time | 0-360 s | 0.5 s |
|  | 142 | Backlash deceleration stopping frequency | $0-400 \mathrm{~Hz}$ | 1 Hz |
|  | 143 | Backlash deceleration stopping time | 0-360 s | 0.5 s |
| Display | 144 | Speed setting switchover | 0/2/4/6/8/10/102/104/106/108/110 | 4 |
|  | 145 | PU display language selection | 0-7 | 1 |
| Variable current limiting | 148 | Stall prevention level at 0 V input | 0-120\% | 110\% |
|  | 149 | Stall prevention level at 10 V input | 0-120\% | 120\% |
| Output current detection | 150 | Output current detection level | 0-120\% | 110\% |
|  | 151 | Output current detection signal delay time | 0-10s | Os |
|  | 152 | Zero current detection level | 0-200\% | 5\% |
|  | 153 | Zero current detection time | 0-1s | 0,5 s |
| Help functions | 154 | Voltage reduction selection during stall prevention operation | 0/1 | 1 |
|  | 155 | RT signal reflection time selection | $0 / 10$ | 0 |
|  | 156 | Stall prevention operation selection | 0-31/100/101 | 0 |
|  | 157 | OL signal output timer | 0-25 s/9999 | 0 |
|  | 158 | AM terminal function selection ${ }^{(1)}$ | 1-3/5/6/8-14/17/21/24/50/52/53 3 | 1 |
|  | 159 | Automatic switchover ON range between commercial power-supply and inverter operation | 0-10 Hz / 9999 | 9999 |
| Aux. function | 160 | User group read selection ${ }^{(1)}$ | 0/1/9999 | 9999 |
|  | 161 | Frequency setting/key lock operation selection | 0/1/10/11 | 0 |
| Restart | 162 | Automatic restart after instantaneous power failure selection | 0/1/10/11 | 0 |
|  | 163 | First cushion time for restart | $0-20 \mathrm{~s}$ | Os |
|  | 164 | First cushion voltage for restart | 0-100\% | 0\% |
|  | 165 | Stall prevention operation level for restart | 0-120\% | 110\% |
| Output current detection | 166 | Output current detection signal retention time | 0-10s/9999 | 0.15 |
|  | 167 | Output current detection operation selection | 0/1 | 0 |
| Aux. functions | 168 | Parameter for manufacturer setting. Do not make setting! | - | - |
|  | 169 |  | - | - |
| Cumulative monitor clear | 170 | Cumulative power meter clear | 0/10/9999 | 9999 |
|  | 171 | Operation hour meter clear | 0/9999 | 9999 |
| User functions | 172 | User group registered display/batch clear | 9999 (0-16) | 0 |
|  | 173 | User group registration | 0-999 / 9999 | 9999 |
|  | 174 | User group clear | 0-999 / 9999 | 9999 |
| Terminal functions selection | 178 | STF terminal function selection | $\begin{gathered} 0-8 / 10-12 / 14 / 16 / 24 / 25 / \\ 37 / 60 / 62 / 64-67 / 9999 \end{gathered}$ | 60 |
|  | 179 | STR terminal function selection | $\begin{gathered} 0-8 / 10-12 / 14 / 16 / 24 / 25 / \\ 37 / 61 / 62 / 64-67 / 9999 \end{gathered}$ | 61 |
| Terminal functions selection | 180 | RL terminal function selection | $\begin{gathered} 0-8 / 10-14 / 16 / 24 / 25 / 37 / \\ 62 / 64-67 / 9999 \end{gathered}$ | 0 |
|  | 181 | RM terminal function selection |  | 1 |
|  | 182 | RH terminal function selection |  | 2 |
|  | 183 | RT terminal function selection |  | 3 |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Terminal functions selection | 184 | AU terminal function selection | 0-8/10-14/16/24/25/37/62-67/9999 | 4 |
|  | 185 | JOG terminal function selection | $\begin{gathered} 0-8 / 10-14 / 16 / 24 / 25 / \\ 37 / 62 / 64-67 / 9999 \end{gathered}$ | 5 |
|  | 186 | CS terminal function selection |  | 6 |
|  | 187 | MRS terminal function selection |  | 24 |
|  | 188 | STOP terminal function selection |  | 25 |
|  | 189 | RES terminal function selection |  | 62 |
|  | 190 | RUN terminal function selection | $\begin{gathered} 0-5 / 7 / 8 / 10-19 / 25 / 26 / 45-47 / 64 / \\ 70-78 / 90-96 / 98 / 99 / 100-105 / 107 / \\ 108 / 110-116 / 125 / 126 / 145-147 / \\ 164 / 170 / 190-196 / 198 / 199 / 9999(6) \end{gathered}$ | 0 |
|  | 191 | SU terminal function selection |  | 1 |
|  | 192 | IPF terminal function selection |  | 2 |
|  | 193 | OL terminal function selection |  | 3 |
|  | 194 | FU terminal function selection |  | 4 |
|  | 195 | ABC1 terminal function selection | $\begin{gathered} 0-5 / 7 / 8 / 10-19 / 25 / 26 / 45-47 / 64 / \\ 70-78 / 90 / 91 / 94-96 / 98 / 99 / 100-105 / \\ 107 / 108 / 110-116 / 125 / 126 / 145-147 / \\ 164 / 170 / 190 / 191 / 194-196 / \\ 198 / 199 / 99996 \end{gathered}$ | 99 |
|  | 196 | ABC2 terminal function selection |  | 9999 |
| Multi-speed setting | 232 | Multi-speed setting (speed 8) ${ }^{(1)}$ | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 233 | Multi-speed setting (speed 9) ${ }^{(1)}$ | $0-400 \mathrm{~Hz}$ / 9999 | 9999 |
|  | 234 | Multi-speed setting (speed 10) ${ }^{(1)}$ | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 235 | Multi-speed setting (speed 11) ${ }^{(1)}$ | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 236 | Multi-speed setting (speed 12) ${ }^{(1)}$ | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 237 | Multi-speed setting (speed 13) ${ }^{(1)}$ | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
|  | 238 | Multi-speed setting (speed 14) ${ }^{(1)}$ | $0-400 \mathrm{~Hz}$ / 9999 | 9999 |
|  | 239 | Multi-speed setting (speed 15) ${ }^{(1)}$ | $0-400 \mathrm{~Hz} / 9999$ | 9999 |
| Help functions | 240 | Soft-PWM operation selection ${ }^{(1)}$ | $0 / 1$ | 1 |
|  | 241 | Analog input display unit switchover ${ }^{(1)}$ | 0/1 | 0 |
|  | 242 | Terminal 1 added compensation amount (terminal 2) | 0-100\% | 100\% |
|  | 243 | Terminal 1 added compensation amount (terminal 4) | 0-100\% | 75\% |
|  | 244 | Cooling fan operation selection | 0/1 | 0 |
| Slip compensation | 245 | Rated slip | 0-50\% / 9999 | 9999 |
|  | 246 | Slip compensation time constant | 0,01-10s | 0.55 |
|  | 247 | Constant-output region slip compensation selection | 0/9999 | 9999 |
| Aux. functions | 250 | Stop selection | 0-100 s/1000-1100 s/8888/9999 | 9999 |
|  | 251 | Output phase failure protection selection | 0/1 | 1 |
|  | 252 | Override bias | 0-200\% | 50\% |
|  | 253 | Override gain | 0-200\% | 150\% |
| Life check | 255 | Life alarm status display | (0-15) | 0 |
|  | 256 | Inrush current suppression circuit life display | (0-100\%) | 100\% |
|  | 257 | Control circuit capacitor life display | (0-100\%) | 100\% |
|  | 258 | Main circuit capacitor life display | (0-100\%) | 100\% |
|  | 259 | Main circuit capacitor life measuring | 0/1 | 0 |
| Special functions | 260 | PWM frequency automatic switchover | 0/1 | 1 |
| Power failure stop | 261 | Power failure stop selection | 0/1/2 | 0 |
|  | 262 | Subtracted frequency at deceleration start | $0-20 \mathrm{~Hz}$ | 3 Hz |
|  | 263 | Subtraction starting frequency | $0-120 \mathrm{~Hz} / 9999$ | 50 Hz |
|  | 264 | Power-failure deceleration time 1 | 0-360 s/0-3600 s | 5 s |
|  | 265 | Power-failure deceleration time 2 | $0-360$ s/0-3600 s/9999 | 9999 |
|  | 266 | Power failure deceleration time switchover frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
| Other functions | 267 | Terminal 4 input selection | 0/1/2 | 0 |
|  | 268 | Monitor decimal digits selection ${ }^{(1)}$ | 0/1/9999 | 9999 |
|  | 269 | Parameter for manufacturer setting. Do not make setting! | - | - |
| Communication functions | 331 | RS-485 communication station | $\begin{gathered} 0-31 \\ (0-247) \end{gathered}$ | 0 |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
| Communication functions | 332 | RS-485 communication speed | 3/6/12/24/48/96/192/384 | 96 |
|  | 333 | RS-485 communication stop bit length | 0/1/10/11 | 1 |
|  | 334 | RS-485 communication parity check selection | 0/1/2 | 2 |
|  | 335 | RS-485 communication number of retries | 0-10/9999 | 1 |
|  | 336 | RS-485 communication check time interval | 0-999.8 s / 9999 | 0 |
|  | 337 | RS-485 communication waiting time setting | 0-150 ms / 9999 | 9999 |
|  | 338 | Communication operation command source | 0/1 | 0 |
|  | 339 | Communication speed command source | $0 / 1$ | 0 |
|  | 340 | Communication startup mode selection | 0/1/2/10/12 | 0 |
|  | 341 | RS-485 communication CR/LF selection | 0/1/2 | 1 |
| Aux. functions | 342 | Communication E $\mathrm{E}^{2}$ PROM write selection | 0/1 | 0 |
|  | 343 | Communication error count | - | 0 |
| Remote outputs | 495 | Remote output selection | 0/1 | 0 |
|  | 496 | Remote output data 1 (1) | 0-4095 | 0 |
|  | 497 | Remote output data $2{ }^{(1)}$ | 0-4095 | 0 |
| Maintenance functions | 503 | Maintenance timer | 0 (1-9998) | 0 |
|  | 504 | Maintenance timer alarm output set time | 0-9998 / 9999 | 9999 |
| Communication functions | 549 | Protocol selection | 0/1 | 0 |
|  | 550 | NET mode operation command source selection | 0/1/9999 | 9999 |
|  | 551 | PU mode operation command source selection | 1/2 | 2 |
| Current average monitor | 555 | Current average time ${ }^{(1)}$ | $0.1-1.0 \mathrm{~s}$ | 1 s |
|  | 556 | Data output mask time ${ }^{(1)}$ | 00,0-20,0 s | Os |
|  | 557 | Current average value monitor signal output reference current ${ }^{(1)}$ | $0-500 \mathrm{~A} / 0-3600 \mathrm{~A}^{(2)}$ | Rated inverter current |
|  | 563 | Energization time carrying-over times | (0-65535) | 0 |
|  | 564 | Operating time carrying-over times | (0-65535) | 0 |
| Aux. functions | 570 | Multiple rating setting | $0 / 1$ | 1 |
|  | 571 | Holding time at a start | 0.0-10.0 s / 9999 | 9999 |
|  | 573 | 4 mA Input check selection | 1/9999 | 9999 |
| PID Sleep function | 575 | Output interruption detection time | 0-3600 / / 9999 | 1 s |
|  | 576 | Output interruption detection level | $0-400 \mathrm{~Hz}$ | 0 Hz |
|  | 577 | Output interruption release level | 900-1100\% | 1000\% |
| Advanced PID control | 578 | Auxiliary motor operation selection | $0 / 1 / 2 / 3$ | 0 |
|  | 579 | Motor switchover selection | $0 / 1 / 2 / 3$ | 0 |
|  | 580 | MC switching interlock time | 0-100s | 1 s |
|  | 581 | Start waiting time | $0-100 \mathrm{~s}$ | 1 s |
|  | 582 | Auxiliary motor connection-time deceleration time | 0-3600 s | 1 s |
|  | 583 | Auxiliary motor disconnection-time acceleration time | $0-3600 \mathrm{~s} / 9999$ | 1 s |
|  | 584 | Auxiliary motor 1 starting frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
|  | 585 | Auxiliary motor 2 starting frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
|  | 586 | Auxiliary motor 3 starting frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
|  | 587 | Auxiliary motor 1 stopping frequency | $0-400 \mathrm{~Hz}$ | OHz |
|  | 588 | Auxiliary motor 2 stopping frequency | $0-400 \mathrm{~Hz}$ | OHz |
|  | 589 | Auxiliary motor 3 stopping frequency | $0-400 \mathrm{~Hz}$ | 0 Hz |
|  | 590 | Auxiliary motor start detection time | $0-3600 \mathrm{~s}$ | 5 s |
|  | 591 | Auxiliary motor stop detection time | $0-3600 \mathrm{~s}$ | 5 s |
| Traverse function | 592 | Traverse function selection | 0/1/2 | 0 |
|  | 593 | Maximum amplitude amount | 0-25\% | 10\% |
|  | 594 | Amplitude compensation amount during deceleration | 0-50\% | 10\% |
|  | 595 | Amplitude compensation amount during acceleration | 0-50\% | 10\% |
|  | 596 | Amplitude acceleration time | 0.1-3600 s | 5 s |
|  | 597 | Amplitude deceleration time | $0.1-3600 \mathrm{~s}$ | 5 s |


| Function | Parameter | Meaning | Setting range | Default setting |
| :---: | :---: | :---: | :---: | :---: |
|  | 611 | Acceleration time at a restart | 0-3600 s/9999 | $5 \mathrm{~s} / 15 \mathrm{~s}^{(2)}$ |
|  | 867 | AM output filter | 0-5s | 0.01 s |
|  | 869 | Current output filter | 0-5s | 0,02s |
|  | 872 | Input phase failure protection selection | 0/1 | 0 |
| Regeneration avoidance function | 882 | Regeneration avoidance operation selection | 0/1 | 0 |
|  | 883 | Regeneration avoidance operation level | $300-800 \mathrm{~V}$ | 760 V DC |
|  | 884 | Regeneration avoidance at deceleration detection sensitivity | 0-5 | 0 |
|  | 885 | Regeneration avoidance compensation frequency limit value | 0-10 Hz / 9999 | 6 Hz |
|  | 886 | Regeneration avoidance voltage gain | 0-200\% | 100\% |
| Free parameter | 888 | Free parameter $1{ }^{(1)}$ | 0-9999 | 9999 |
|  | 889 | Free parameter $2{ }^{(1)}$ | 0-9999 | 9999 |
| Energy saving monitor | 891 | Cumulative power monitor digit shifted times ${ }^{(1)}$ | 0-4/9999 | 9999 |
|  | 892 | Load factor ${ }^{(1)}$ | 30-150\% | 100\% |
|  | 893 | Energy saving monitor reference (motor capacity) ${ }^{(1)}$ | $0.1-55 \mathrm{~kW} / 0-3600 \mathrm{~kW}{ }^{(2)}$ | Motor capacity at 120\% / 150\% overload capacity |
|  | 894 | Control selection during commercial power-supply operation ${ }^{(1)}$ | 0/1/2/3 | 0 |
|  | 895 | Power saving rate reference value ${ }^{(1)}$ | 0/1/9999 | 9999 |
|  | 896 | Power unit cost ${ }^{(1)}$ | 0-500 / 9999 | 9999 |
|  | 897 | Power saving monitor average time ${ }^{(1)}$ | 0/1-1000 h/9999 | 9999 |
|  | 898 | Power saving cumulative monitor clear ${ }^{(1)}$ | 0/1/10/9999 | 9999 |
|  | 899 | Operation time rate (estimated value) ${ }^{(1)}$ | 0-100\% / 9999 | 9999 |
| Calibration function | CO (900) | CA terminal calibration ${ }^{(1)}$ | Calibration range | - |
|  | C1 (901) | AM terminal calibration ${ }^{(1)}$ | Calibration range | - |
|  | C2 (902) | Terminal 2 frequency setting bias frequency | $0-400 \mathrm{~Hz}$ | OHz |
|  | C3 (902) | Terminal 2 frequency setting bias | 0-300\% | 0\% |
|  | 125 (903) | Terminal 2 frequency setting gain frequency | $0-400 \mathrm{~Hz}$ | 0 Hz |
|  | C4 (903) | Terminal 2 frequency setting gain | 0-300\% | 100\% |
|  | C5 (904) | Terminal 4 frequency setting bias frequency | $0-400 \mathrm{~Hz}$ | 0 Hz |
|  | C6 (904) | Terminal 4 frequency setting bias | 0-300\% | 20\% |
|  | 126 (905) | Terminal 4 frequency setting gain frequency | $0-400 \mathrm{~Hz}$ | 50 Hz |
|  | C7 (905) | Terminal 4 frequency setting gain | 0-300\% | 100\% |
| Analog current output calibration function | C8 (930) | Current output bias signal | 0-100\% | 0\% |
|  | C9 (930) | Current output bias current | 0-100\% | 0\% |
|  | C10 (931) | Current output gain signal | 0-100\% | 100\% |
|  | C11 (931) | Current output gain current | 0-100\% | 100\% |
|  | 989 | Parameter copy alarm release | $10 / 100{ }^{(2)}$ | $10 / 100{ }^{(2)}$ |
| Help functions | 990 | PU buzzer control ${ }^{(1)}$ | $0 / 1$ | 1 |
|  | 991 | PU contrast adjustment ${ }^{(1)}$ | 0-63 | 58 |
|  | PR.CL | Parameter clear | 0/1 | 0 |
|  | ALLC | All parameter clear | 0/1 | 0 |
|  | Er.CL | Alarm history clear | 0/1 | 0 |
|  | PCPY | Parameter copy | $0 / 1 / 2 / 3$ | 0 |

Notes:
(1) These parameters can be changed during operation if parameter 77 is set to 0 (factory setting).
(2) The possible setting values depend on the capacity class of the inverter.
${ }^{(3)}$ A setting of 9 is possible on models 01800 and above.
(4) This setting is possible on models 01800 and above.
(5) Setting of 100 to 103,114 to 117 are possible on models 01800 and above.
(6) Setting of 7 and 107 are possible on models 01800 and above.

## Protective Functions Overview

The frequency inverter FR－F 740 provides a large number of protective functions that protect the drive and the inverter against damage in case of any malfunction．

If an error occurs，the output of the inverter is suspended and the control panel returns an error message．

| Display on operation panel FR－DU07 | Meaning | Description | Remedy |
| :---: | :---: | :---: | :---: |
| HOLD ${ }^{(1)}$ | Operation panel lock | Operation lock mode ist set． | Press and hold the MODE key for 2 s to enable the operation panel． |
| Er1 ${ }^{(1)}$ | Write disable error | This error occurs when a write operation is attempted with Pr． $77=1$ ，the frequency jump ranges overlap，the ranges for the flexible 5 －point V／f characteristic overlap or no communication is possi－ ble between the control panel and the frequency inverter． | Check the setting of Pr． 77, Pr． 31 to 36 Pr． 100 to 109 and the connection of the operation panel and inverter． |
| Er2 ${ }^{(1)}$ | Write error | This error occurs when a write operation is attempted with the inverter in operation when the value of Pr． 77 ＜＞ 2 and an STF or STR start signal is active． | Check the setting of Pr．77．The frequency inverter must be in stop mode． |
| Er3 ${ }^{(1)}$ | Calibration error | Analog input bias and gain calibration values are too close． | Check the parameter C3， 4 ， C 6 and $\mathrm{C7}$ |
| Er4 ${ }^{(1)}$ | Mode designation error | This error occurs when you try to set a parameter in NET mode when PR． 77 ＜＞2． | Check the setting of Pr．77．Set the operating mode to operation via control panel． |
| re1 ${ }^{(1)}$ | Parameter read error | An error occurred in the E2PROM on the operation panel side during parameter copy reading． | Repeat the copy operation．Check the control panel connections．Please contact your nearest MITSUBISHI ELECTRIC representative if the error occurs repeatedly． |
| rE2 ${ }^{(1)}$ | Parameter write error | An error occurred in the E2PROM on the operation panel side during parameter copy writing． | Repeat the copy operation with the inverter stopped．Check the control panel connections． Please contact your nearest MITSUBISHI ELEC－ TRIC representative if the error occurs repeat－ edly． |
| rE3 ${ }^{(1)}$ | Parameter verification error | Data on the operation panel side and inverter side are different．An error occurred in the E2PROM on the operation panel side during parameter verification． | Press the SET key to continue verification．Check the control panel connections．Please contact your nearest MITSUBISHI ELECTRIC representa－ tive if the error occurs repeatedly． |
| rE4 ${ }^{(1)}$ | Model error | A different model was used for parameter write and verification during parameter copy． | Use the same model for parameter copy and verification． |
| Err． | Error | The RESET signal is active or there is an error in the communication between the frequency inverter and the control panel． | Deactivated the RESET signal．Check the con－ nections between the control panel and the frequency inverter． |
| OL | Overcurrent during acceleration | If a current of more than $110 \%{ }^{(2)}$ of the rated inverter current flows in the motor，this function stops the increase in frequency until the overload current reduces to prevent the inverter from re－ sulting in overcurrent shut－off．When the overload current has reduced below $110 \%$ ，this function increases the frequency again． | Increase the stall prevention operation level with Pr． 22 ＂stall prevention operation level＂ or disable stall prevention with Pr． 156 ＂stall prevention operation selection＂． |
|  | Overcurrent during con－ stant speed operation | If a current of more than $110 \%{ }^{(2)}$ of the rated inverter current flows in the motor，this function low－ ers the frequency until the overload current reduces to prevent overcurrent shut－off．When the over－ load current has reduced below $110 \%$ ，this function increases the frequency up to the set value． |  |
|  | Overcurrent during deceleration | If a current of more than $110 \%{ }^{(2)}$ of the rated inverter current flows in the motor，this function stops the decrease in frequency until the overload current reduces to prevent theinverter from re－ sulting in overcurrent shut－off．When the overload current has reduced below $110 \%$ ，this function decreases the frequency again． |  |
| oL | Overvoltage during deceleration | If the regenerative energy of the motor increases too much to exceed the brake capability，this func－ tion stops the decrease in frequency to prevent overvoltage shut－off．As soon as the regenerative energy has reduced，deceleration resumes． | Increase the deceleration time with Pr． 8 ＂decel－ eration time＂． |
| rb | Regenerative brake prealarm | Too much energy is being fed into the brake resistor（model 01800 and above）． | Increase the deceleration time．Check the Pr． 30 and 70 values． |
| PS | Inverter was stopped via control panel | STOP key on the control panel was pressed during external operating mode． | Check the parameter 77. |
| TH | Electronic thermal relay function prealarm | The prealarm of the electronic motor protection switch has activated． | The load or number of work cycles is too high． |
| MT ${ }^{(1)}$ | Maintenance signal output | The cumulated operating time has reached the preset value． | The value in Pr． 503 is larger than the setting of Pr． 504. |
| CP | Parameter copy | Attempt to perform a copy operation from a frequency inverter model 01160 or lower to a model 01800 or higher． | Reset parameters $9,30,51,52,54,5657,61,70$ ， $72,80,90,158,190-196$ and 893 ． |
| FN | Fan fault | The cooling fan is not operating as set in Pr． 244. | Replace the cooling fan． |



| Display on <br> operation panel <br> FR－DU07 | Meaning |  | Rescription | Remedy |
| :---: | :--- | :--- | :--- | :--- |

[^2]
## Resetting Methods

When a protective function is activated, the output of the inverter is switched off. The motor coasts to a halt. The output remains switched off until the error cause is eliminated and the inverter reset. The inverter can be reset following four different methods:

- Switch the power supply OFF and ON again.
- Switch the reset signal ON for at least 0.1 s .
- Press the RESET key on the control panel.
- Use the automatic restart function (Pr. 65, Pr. 67-69)

If the reset signal is ON continuously, the operation panel FR-DU07 returns an error message while the control unit FR-PU04 indicates that the reset procedure is in progress.
When a protective function is activated, the operation panel FR-DU07 returns an error code as listed in the table above.
The control panel FR-PU04 returns error messages in clear.

If on occurrence of an error the input protection contactor is toggled the error message cannot be retained, since there is no power supply for the control circuit. If the error message is intended to be retained in spite of an activation of the protectve contactor, the control circuit has to be supplied by a separate power supply.

## Separate power supply for the control circuit

The figure on the right shows the connection of the separate $380-480 \mathrm{~V} \mathrm{AC}$
(-15\%/+10\%) power supply for the control circuit. The current consumption is 2 A .
Prior to the connection remove the two short bars upon L11 and L21 on the inverter.
Please refer to the according manual for a precise description of the connection.


## Application Examples

## Ventilation system



Ventilation systems of modern painting plants often have high-powered motors. This makes them an ideal application for frequency inverters, which can replace the contactors and "soft starter" systems with bypass circuits that are often used in these installations.

The higher initial investment involved in installing frequency inverters can pay for itself in a very short time because of the many benefits of this solution.

## Benefits

- Reduction of switch-on and start-up currents, also compared to soft starter systems, thus reducing peak load power costs.
- Gentle flying starts for fans that are already rotating in duct drafts, thus increasing general system service life.
- Motor speed reduction for lower throughput at low demand times without dampers for significant power savings.
- No need for bypass contactors.
- Motor pre-heating is possible.
- With properly-dimensioned drive systems and brake modules you can also stop the fans quickly, for example when fir extinguishing gas needs to be used.


## Specifications

- Drive system with 4-pole motor, 132 kW
- Frequency inverter: FR-F 740-03250 EC
- Acceleration/braking times: 360 s
- S-ramp programming
- Flying start function
- Optimum Excitation Control function
- Regeneration avoidance function
- Control via analog signal (0-10 V)
- Output frequency range $22-50 \mathrm{~Hz}$
- Average power consumption of conventional system per 24 h: 2,890 kWh
- Average power consumption of frequency inverter system per 24 h : 2,610 kWh



## Stamping press

(small metal parts production)


Retrofitting this stamping press with the FR-F 740 frequency inverter brought significant energy savings. The secret is the FR-F 740 's intelligent Flux Optimisation mode. During the phase of the stamping sequence with low overload requirements Flux Optimisation mode quickly reduces the motor voltage.
Die kurze Regelzeit der Flux-Optimisation ist der Schlüssel zum Erfolg: Die Spannung wird für den nächsten Stanz-Vorgang wieder angehoben.

## Specifications

- Manually-operated stamping press with 400 tons stamping pressure
- Powered by a 4 -pole motor ( 55 kW )
- Frequency inverter: FR-F 740-75k
- Operation: The press is operated with the motor running at constant speed. During the stamping sequence the power required for punching out the metal components is transferred briefly to the punch by engaging a magnetic clutch coupling.
- Power consumption:

As the graphs below show, the power consumption of the press is identical for both pressing operations.
However, the low load cycle power con-
sumption (magnetic clutch disengaged) drops when a frequency inverter is used:
Normal operation of the stamping press: 7.8 kW
Stamping press operated with frequency inverter: 5.3 kW

- Depending on the design of the drive system used it may also be necessary to use an (optional) brake resistor in applications like this.


## Benefits

- Energy savings

Flux optimisation mode prevents unnecessary power consumption. Energy is conserved in every phase of the cycle when the motor load is less than $100 \%$.

- Simple installation

Retrofitting applications like this stamping press with a frequency inverter is very quick and trouble-free.

- Enhanced precision The option of variable motor speed provides better control over your application and thus improves manufacturing precision and product quality.

Normal operation without Flux Optimisation


Operation of the press with Flux Optimisation
kW


## Internal and External Options

A large number of options allows an individual adoption of the inverter to the according task. The options can be installed quickly and easily. Detailed information on installation and functions is included in the manual of the options. The options can be divided into two major categories:

- Internal options
- External options



## Internal options

The internal options comprise input and output extensions as well as communications options supporting the operation of the inverter within a network or connected to a personal computer or PLC.

| Option |  | Type | Description | Remarks/Specifications | Art. no. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Internal options | 16-bit digital input | FR-A7AX | Interface for the input of the frequency setting via 4 -digit BCD or 16 -bit binary code, setting of gain and bias supported. | Input:24V DC; 5 mA ; open collector or switching signal, sink or source logic | 156775 |
|  | Digital output |  | Selectable of 43 standard output signals of the inverter can be output at the open collector. The outputs are isolated with optocouplers. | Output load: 24V DC; 0.1 A , sink or source logic |  |
|  | Expansion analog output | FR-A7AY | Selectable 2 of 18 additional signals (e.g. output frequency, output voltage, output current) can be output and indicated at the FM / AM output. <br> Display on measuring gauge: 20 mA DC or $5 \mathrm{~V}(10 \mathrm{~V}) \mathrm{DC}$ | Output:max. $0-10 \mathrm{~V}$ DC; $0-20 \mathrm{~mA}$; Resolution: 3 mV at voltage output, $1 \mu \mathrm{~A}$ at current output, accuracy: $\pm 10 \%$ | 156776 |
|  | Relay output | FR-A7AR | Selectable 3 of 43 standard output signals of the inverter can be output through relay terminals. | Switching load: $\begin{array}{ll}230 \mathrm{~V} \mathrm{AC} / 0.3 \mathrm{~A}, \\ & 30 \mathrm{VDC} / 0.3 \mathrm{~A}\end{array}$ | 156777 |
|  | CC-Link | FR-A7NC | Option board for the integration of a frequency inverter into a CC-Link network. The operation, display functions, and parameter settings can be controlled by a PLC. | Maximum transfer distance: 1200 m (at 156 kBaud ) | 156778 |
|  | Communi- LonWorks | FR-A7NL | Option board for integration of a frequency inverter in a LonWorks network. Operation, display functions and parameter settings can be controlled by a computer (PC etc.) or a PLC. | Connection of up to 64 inverters supported. Maximum transfer rate: 78 kBaud | 156779 |
|  | cations Profibus/DP | FR-A7NP | Option board for the integration of a frequency inverter into a Profibus/DP network. The operation, display functions, and parameter settings can be controlled by a computer (PC etc.) or a PLC. | Connection of up to 126 inverters supported. Maximum transfer rate: 12 MBaud | 158524 |
|  | DeviceNet ${ }^{\text {TM }}$ | FR-A7ND | Option board for the integration of a frequency inverter into a DeviceNet. The operation, display functions, and parameter settings can be controlled by a computer (PC etc.) or a PLC. | Maximum transfer rate: 10 MBaud | 158525 |

## External Options

In addition to the FR-PU04 control panel that enables interactive operation of the frequency inverter the available external options also include additional EMC noise
filters, reactors for improving efficiency and brake units with brake resistors.

| Option |  | Type | Description | Remarks/Specifications | Art. no. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Externe Optionen | Control panel (8 languages) | FR-PU04 | Interactive control panel with LCD display. | Refer to p .18 for detailed descriptio | 67735 |
|  | Connecting cable for remote control panel | FR-A5 CBL | Cable for a remote connection of the control panel FR-DU07 or FR-PU04. | Available length: $1 ; 2.5$ and 5 m | $\begin{gathered} 1 \mathrm{~m}: 70727 \\ 2.5 \mathrm{~m}: 70728 \\ 5 \mathrm{~m}: 70729 \end{gathered}$ |
|  | Adapter | FR-ADP | Connection adapter for FR-DU07 | Required for remote connection of the FR-DU07 with FR-A5CBL | 157515 |
|  | Connection cable | SC-FR PC | Communications cable for RS232 or RS485 interface to connect an external personal computer | Length 3 m ; can be used for example with the VFD setup software | 88426 |
|  | USB-RS232 converter |  | Port converter adapter cable from RS-232 to USB | USB specification 1.1,0.35 m long | 155606 |
|  | VFD setup software | FR-SW0-SETUP-W $\square$ | Parameterization and setup software for the whole FR-F 700 series as well as all other Mitsubishi inverter series. | English/German | 159746 |
|  | EMC noise filter | $\begin{aligned} & \text { FFR - } \square \square, \\ & \text { FN- } \square \square \end{aligned}$ | Noise filter for compliance with EMC directives. | Refer to p. 36 for detailed description | see p. 36 |
|  | DC converter circuit choke coil | MT-HEL ${ }^{(1)}$ | DC reactor for compensation of voltage fluctuations. | Refer to p. 37 for detailed description | see p. 37 |
|  | Mains power chokes | FR-BAL-B | For increased efficiency, reduction of mains feedback and compensation of voltage fluctuations. | Refer to p. 37 for detailed description | see p. 37 |
|  | Brake units | MT-BU 5 , BU-UFS | For an improvement of the brake capacity.For high inertia loads and active loads. Used in combination with a resistor unit. | Refer to p. 38 and $p .39$ for detailed description | $\begin{gathered} \text { see } p .38 \text { and } \\ \text { p. } 39 \end{gathered}$ |
|  | External brake resistors | MT-BR 5, RUFC | To improve the brake capacity of the inverter; is used in combination with a brake unit | Refer to p. 38 ans p .39 for detailed description | $\begin{aligned} & \text { see } .38 \text { ans } \\ & \text { p. } 39 \end{aligned}$ |

(1) $A D C$ reactor is included as standard equipment with frequency inverters FR-F 740-01800 through 12120. These reactors are essential for operation and must be installed.

```
Mounting examples for internal options
```



## Noise Filters for FR－F 740－00023 to FR－F 740－01160



## Environment 1 noise filters

The noise filters listed below make it possi－ ble to comply with the requirements for Environment 1 （unrestricted distribution） with shielded motor cables up to 20 m long and the requirements of Environment 1 （restricted distribution）with shielded mo－ tor cables up to 100 m long．This also provi－ des compliance with the 100A limits for Environment 2 with shielded cables up to 100 m long．
The frequency inverters of the FR－F 740 se－ ries are fitted with an integrated EMC noise filter for industrial environments（Environ－ ment 2）．The filters listed here are thus only necessary for these inverters in special ca－ ses．

The FN 3359－$\square \square \square$ filters enable compli－ ance with the requirements for Environ－ ment 1 （restricted distribution）with shiel－ ded motor cables up to 100 m long，and thus also with the requirements for Envi－ ronment 2 with cables of the same length． Th FFR－A540－$\square \square \square$ A－SF100 filters are con－ figured for＂footprint＂installation，which means that the base plate of the frequency inverter is bolted onto the filter unit，so that the entire assembly can then be bol－ ted onto the mounting plate in a switchgear cabinet．

| Filter | Inverter | Power loss ［W］ | Leakage current ［mA］ | $\begin{aligned} & \text { Rated } \\ & \text { current }[A] \end{aligned}$ | Weight［kg］ | Art．no． |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FFR－A540－8A－SF100 | FR－F740－00023－00052 | 5 | ＜30 | 8 | 1.5 | 104741 |
| FFR－A540－16A－SF100 | FR－F740－00083 | 8 | ＜30 | 16 | 1.5 | 104752 |
| FFR－A540－30A－SF100 | FR－F740－00126－00250 | 14 | ＜30 | 30 | 1.8 | 104753 |
| FFR－7740－55A－SF100 | FR－F 740－00310－FR－F740－00380 | 34 | ＜30 | 55 | 3 | 157395 |
| FFR－A540－75A－SF100 | FR－F 740－00470－FR－F740－00620 | 34 | ＜30 | 75 | 4.1 | 104755 |
| FFR－A540－95A－SF100 | FR－F740－00770 | 36 | ＜30 | 95 | 6.7 | 104756 |
| FFR－A540－120A－SF100 | FR－F740－00930 | 34 | ＜30 | 120 | 9.7 | 151881 |
| FFR－A540－180A－SF100 | FR－F740－01160 | 62 | ＜30 | 180 | 10.8 | 104757 |

Noise Filters for FR－F 740－01800 to FR－F 740－12120

|  | Noise filters for high capacities |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | The extreme filters provid noise suppre ments． <br> The FN 3359 suppression The filters ar duced interf | mpact line of FN 3359 he user with an efficient at low room require－ <br> rs are suitable for noise forming to EN 61800－3． <br> signed to reduce cable－in－ ce to levels that comply | ＂Footprint＂installation on the frequency inverter base plate is not possible with the FN3359－$\square \square \square-28 / 99$ filters．These units must be installed next to the frequency in－ verter． |  |  |  |  |
| e | Filter | Inverter | Powerloss ［W］ | Leakage current［mA］ | Rated cur－ rent［A］ | Weight［kg］ | Art．no． |
|  | FN 3359－180－28 | FR－F 740－01800 | 34 | $<6$ | 180 | 6.5 | 141097 |
|  | FN 3359－250－28 | FR－F 740－02160 | 38 | ＜6 | 250 | 7 | 104663 |
|  | FN 3359－400－99 | FR－F 740－02600－FR－F740－03610 | 51 | ＜6 | 400 | 10.5 | 104664 |
|  | FN 3359－600－99 | FR－F 740－04320－FR－F740－05470 | 65 | ＜6 | 600 | 11 | 104665 |
|  | FN 3359－1000－99 | FR－F 740－06100－FR－F740－09620 | 84 | ＜6 | 1000 | 18 | 104666 |
|  | FN 3359－1600－99 | FR－F 740－10940－FR－F740－12120 | 130 | ＜6 | 1600 | 27 | 130229 |

These filters enable compliance with the requirements for Environment 1 （restricted distribution）with shielded motor cables up to 100 m long，and thus also with the requirements of Environment 2 with the same cable lengths．

DC Reactors


## DC link reactors

A DC link reactor is included as standard equipment with frequency inverter models FR-F740-01800 and above. This reactor is essential for the operation of the inverter and must be installed.

The reactors listed below are available as optional equipment for frequency inverter models FR-F740-00023 through 01160.

| Application (inverter) | Reactor | Power loss [W] |  | Weight [kg] | Art. no. |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | at 120\% | at 150\% |  |  |
| FR-F 740-01800 | FR-HEL-H9OK | 128 | 121 | 20 | The DC link reactor MT-HEL is included as standard equipment with the respective frequency inverter. |
| FR-F 740-02160 | FR-HEL-H110K | 138 | 128 | 22 |  |
| FR-F 740-02600 | FR-HEL-H132K | 140 | 138 | 26 |  |
| FR-F 740-03250 | FR-HEL-H160K | 162 | 140 | 28 |  |
| FR-F 740-03610 | FR-HEL-H185K | 245 | 162 | 29 |  |
| FR-F 740-04320 | FR-HEL-H220K | 265 | 245 | 30 |  |
| FR-F 740-04810 | FR-HEL-H250K | 285 | 265 | 35 |  |
| FR-F 740-05470 | FR-HEL-H280K | 315 | 285 | 38 |  |
| FR-F 740-06100 | FR-HEL-H315K | 350 | 315 | 42 |  |
| FR-F 740-06830 | FR-HEL-H355K | 400 | 350 | 46 |  |
| FR-F 740-07700 | FR-HEL-H400K | 460 | 400 | 50 |  |
| FR-F 740-08660 | FR-HEL-H450K | 540 | 460 | 57 |  |
| FR-F 740-09620 | FR-HEL-H500K | 635 | 540 | 67 |  |
| FR-F 740-10940 | FR-HEL-H560K | 770 | 635 | 85 |  |
| FR-F 740-12120 | FR-HEL-H630K | 960 | 770 | 95 |  |

Note:
A three-phase mains supply choke (see below) can also be used as an alternative to the DC link reactor on frequency inverter models FR-F740-01160 and below.

Power Chokes for Three-Phase Current


## Three-phase mains supply chokes

The three-phase mains supply chokes FR-BAL-B- $\square \square \mathrm{k}$ for the frequency inverters FR-A 740 EC compensate voltage fluctuations and simultaneously increase the efficiency.
Applying the appropriate power choke an overall efficiency of up to $90 \%$ can be achieved.

The use of a power choke is especially recommended for mains circuits where high capacities are switched, for example, via thyristors.

| Inverter | Choke | L[mH] | Current [A] | Powerloss <br> $[W]$ | Weight [kg] |
| :--- | :--- | :---: | :---: | :---: | :---: | Art. no. 9.

## Brake Unit MT-BU5



The MT-BU5 external brake units can be used with frequency inverter models FR-F740-01800 and above. These inverters are fitted with a connector via which the MT-BU5 brake unit is controlled directly. This connection also makes it possible for the FR-F740 to handle the protection of the MT-BU5 against thermal overloads.

Brake resistors must be chosen in accordance with your application's requirements. The configurations in the table are only general recommendations. Please consult Mitsubishi Electric for advice on matching the correct brake modules and brake resistors for your application.

| Inverter | Brake unit | Number of required units | Braking torque |
| :--- | :--- | :--- | :--- |
| FR-F740-01800 | MT-BU5-H75 k | $1 \times$ MT-BR5-H75 k | $100 \%, 10 \%$ ED |
| FR-F740-02160-03250 | MT-BU5-H150 k | $2 \times$ MT-BR5-H75 k | 125700 |
| FR-F740-03250-04320 | MT-BU5-H220k | $3 \times$ MT-BR5-H75 k | $100 \%, 10 \%$ ED |
| FR-F740-04320-05470 | MT-BU5-H280 k | $4 \times$ MT-BR5-H75 k | $1200 \%, 10 \%$ ED |
| FR-F740-05470-07700 | MT-BU5-H375 k | $5 \times$ MT-BR5-H75 k | $100 \%, 10 \%$ ED |

## External Brake Resistor MT-BR5 for Brake Unit MT-BU5



The brake resistor MT-BR5 for the frequency inverters FR-F 740 EC/E1 is used exclusively in combination with a brake unit

Important:

- The regenerative brake duty should be set at levels below the permissible brake duty specified in the table above.
- Since the temperature of the brake resistor may exceed $300^{\circ} \mathrm{C}$ take care to provide a sufficient heat dissipation.

| Brake resistor | Regenerative brake duty | Resistance $[\Omega]$ | Alt. no. |
| :---: | :---: | :---: | :---: |
| MT-BR5-H75 k | $6 \%$ | 6.5 | 125699 |

## Brake Units BU－UFS



For a braking torque higher than $20 \%$ or a duty cycle higher than $30 \%$ an external brake unit including the adequate brake resistors has to be installed．
The brake units BU－UFS listed below are cascadable so that the optimum dimensio－ ning can always be achieved．

The brake units here are not fitted with brake resistors，which must be ordered se－ parately（see below）．
The configurations in the table are only ge－ neral recommendations．Please consult Mitsubishi Electric for advice on matching the correct brake modules and brake resis－ tors for your application．

| Inverter | Brake unit | Max．peak current［W］ | Max．instantane－ ous power［kW］ | Max．duty cycle | Art．no． |
| :---: | :---: | :---: | :---: | :---: | :---: |
| FR－F740－00023－00250 | BU－UFS22 | 34 | 25 | 10\％ | 127947 |
| FR－F740－00250－00470 | BU－UFS40 | 55 | 41 | 10\％ | 127948 |
| FR－F740－00470－01160 | BU－UFS110 | 140 | 105 | 5\％ | 127950 |

## Brake Resistors for Brake Unit BU－UFS



Operation panel FR-DU07


All dimensions in mm

## Control panel FR-PU04




All dimensions in mm

## Connection of the control panel

The control panel can be connected to the inverter remotely via the connecting cable type FR-A5-CBL ( $1 \mathrm{~m} ; 2.5 \mathrm{~m} ; 5 \mathrm{~m}$ ). You must only use the original MITSUBISHI ELECTRIC cable. This cable is available as optional accessory. Plug the cable in the according connectors on the control panel and the inverter.
The figure besides shows the pin assignment of the connector plugs.
Never connect fax modems or modular telephone plugs with the connectors.
Otherwise, the inverter might be damaged.

The connection of the control panel can be done with the communications cable SC-FR PC. A connection of the control panel to a personal computer is possible too.

## FR-F 740-00023-00126

## Note:

Models 00023 through 00052 do not have internal fans.


| Type | B | B1 | C | D |
| :--- | :---: | :---: | :---: | :---: |
| FR-F740-00170, <br> FR-F740-00250 | 260 | 245 | 170 | 84 |
| FR-F740-00310, <br> FR-F740-00380 | 300 | 285 | 190 | 101.5 |



FR-F 740-00470 - 00620


All dimensions in mm

FR-F 740-00770-01160


| Type | A | A1 | A2 | B | B1 | C | d |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-F740-00770 | 325 | 270 | 10 | 530 | 10 | 195 | 10 |
| FR-F740-00030, <br> FR-F740-01160 | 435 | 380 | 12 | 525 | 15 | 250 | 12 |



FR-F 740-01800 - 02160


| Type | A | A1 | A2 | B | B1 | C |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-F740-01800 | 435 | 380 | 12 | 550 | 525 | 250 |
| FR-F740-02160 | 465 | 400 | 32,5 | 620 | 595 | 300 |



FR-F 740-02600 - 03610


| Type | B | B1 | C |
| :--- | :---: | :---: | :---: |
| FR-F740-02600 | 595 | 620 | 300 |
| FR-F740-03250, | 715 | 740 | 360 |
| FR-F740-03610 |  |  |  |

FR-F 740-04320 - 08660


All dimensions in mm

| Type | A | A1 | A2 | B | B1 | B2 | C |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-F740-04320 - FR-F740-04810 | 498 | 200 | 49 | 1010 | 984 | 13 | 380 |
| FR-F740-05470 - FR-F740-06830 | 680 | 300 | 40 | 1010 | 984 | 13 | 380 |
| FR-F740-07700 - FR-F740-08660 | 790 | 315 | 80 | 1330 | 1300 | 15 | 440 |



Special Noise Filters FFR-A540-8A-SF100 to FFR-A540-180A-SF100


Noise Filter FN 3359-180-28 and FN 3359-1600-99


| Filter | Inverter <br> FR-F 740 | A B | C | D | E | Weight <br> $[\mathrm{kg}]$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: |
| FN 3359-180-28 | 01800 | 210 | 300 | 185 | 120 | 160 |
| FN 3359-250-28 | 02160 | 230 | 300 | 205 | 120 | 180 |

All dimensions in mm


| Filter | Inverter <br> FR-F 740 | A B | C | D | F | Weight <br> $[\mathrm{kg}]$ |
| :--- | ---: | :---: | :---: | :---: | :---: | :---: |
| FN 3359-400-99 | $02600-03610$ | 260 | 306 | 235 | 120 | 210 |

All dimensions in mm

## Converter Choke FR-HEL-H9OK

$\equiv$


| Choke | A | A1 | B | B1 | C | Weight [kg] |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-HEL-HOOK | 150 | 130 | 340 | 310 | 190 | 20 |

All dimensions in mm

Converter Choke FR-HEL-H110K - 160K
$\overline{\bar{Z}}$


| Choke | A | A1 | B | B1 | C | S | S1 | Weight [kg] |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FR-HEL-H11OK | 150 | 130 | 340 | 310 | 195 | M6 | M6 | 22 |
| FR-HEL-H132K | 175 | 150 | 405 | 370 | 200 | M8 | M6 | 26 |
| FR-HEL-H160K | 175 | 150 | 405 | 370 | 205 | M8 | M6 | 28 |

All dimensions in mm

Converter Choke FR-HEL-H185K - 355K
$\equiv$


| Choke | A | A1 | B | B1 | C | S | S1 | S2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | $\varnothing$ | Weight [kg] |  |  |  |  |  |  |
| FR-HEL-H185K | 175 | 150 | 405 | 370 | 240 | M8 | M6 | - |
| M12 | 29 |  |  |  |  |  |  |  |
| FR-HEL-H220K | 175 | 150 | 405 | 370 | 240 | M8 | M6 | M6 |
| M12 | 30 |  |  |  |  |  |  |  |
| FR-HEL-H250K | 190 | 165 | 440 | 400 | 250 | M8 | M8 | M8 |
| M12 | 35 |  |  |  |  |  |  |  |
| FR-HEL-H280K | 190 | 165 | 440 | 400 | 255 | M8 | M8 | M8 |
| M16 | 38 |  |  |  |  |  |  |  |
| FR-HEL-H315K | 210 | 185 | 495 | 450 | 250 | M10 | M8 | M8 |
| M16 | 42 |  |  |  |  |  |  |  |
| FR-HEL-H355K | 210 | 185 | 495 | 450 | 250 | M10 | M8 | M8 |
| M16 | 46 |  |  |  |  |  |  |  |

## Converter Choke FR-HEL-H400K - 450K



| Choke | A | C | Weight [kg] |
| :--- | :---: | :---: | :---: |
| FR-HEL-H400K | 235 | 250 | 50 |
| FR-HEL-H450K | 240 | 270 | 57 |

## Converter Choke FR-HEL-H500K - 630K



| Choke | B | C | C1 | Weight [kg] |
| :--- | :---: | :---: | :---: | :---: |
| FR-HEL-H500K | 345 | 455 | 405 | 67 |
| FR-HEL-H560K | 360 | 460 | 410 | 85 |
| FR-HEL-H630K | 360 | 460 | 410 | 95 |

## Brake Units MT-BU5



Brake Units BU-UFS


| Brake unit | A | A $^{\prime}$ | B | B $^{\prime}$ | C | Weight [kg] |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| BU-UFS22 | 100 | 50 | 250 | 240 | 175 | 2.5 |
| BU-UFS40 | 100 | 50 | 250 | 240 | 175 | 2.5 |
| BU-UFS110 | 107 | 50 | 250 | 240 | 195 | 3.9 |

## External Brake Resistor MT-BR5



| Brake resistor | A | A $^{\prime}$ | B | B $^{\prime}$ | C | C' | Weight [kg] |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MT-BR5-H75 k | 510 | 480 | 885 | 800 | 465 | 300 | 70 |

All dimensions in mm

## External Brake Resistor RUFC



| Brake resistor | A | A $^{\prime}$ | B | Weight [kg] |
| :--- | :---: | :---: | :---: | :---: |
| RUFC22 | 310 | 295 | 75 | 4.7 |
| RUFC40 | 365 | 350 | 75 | 9.4 |
| RUFC110 | 365 | 350 | 75 | 18.8 |



Notes when ordering:
When ordering, please use only the type designations and order numbers shown in this catalogue.

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[^0]:    * The parameter copy function and the parameter and alarm display functions are restricted when the panel is connected to the FR-F 740.

[^1]:    * The FR-F700 is supported by Version 3.1 and above (available from January 2005)

[^2]:    （1）If when employing the control panel FR－PU04 one of the errors HOLD，Er1 to 4，rE1 to 4，MT，E．ILF，E．PTC，E．PE2，E．CDO，E．IOH，E．SER，E．AIE，E． 13 occurs，then Fault 14 will be displayed．
    （2）When the overload capacity is $150 \%$ the limit is $120 \%$ ．

